

The giant graviton on $AdS_4 \times \mathbb{CP}^3$ - another step towards the emergence of geometry

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ABSTRACT: We construct the giant graviton on $AdS_4 \times \mathbb{CP}^3$ out of a four-brane embedded in and moving on the complex projective space. This configuration is dual to the totally anti-symmetric Schur polynomial operator $\chi_R(A_1 B_1)$ in the 2+1-dimensional, $\mathcal{N} = 6$ super Chern-Simons ABJM theory. We demonstrate that this BPS solution of the D4-brane action is energetically degenerate with the point graviton solution and initiate a study of its spectrum of small fluctuations. Although the full computation of this spectrum proves to be analytically intractable, by perturbing around a “small” giant graviton, we find good evidence for a dependence of the spectrum on the size, α_0 , of the giant. This is a direct result of the changing shape of the worldvolume as it grows in size.

KEYWORDS: D-branes, Giant gravitons, AdS/CFT correspondence.

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1. Introduction

Lab·o·ra·to·ry /'labre, tōrē / *noun: any place, situation, object, set of conditions, or the like, conducive to controlled experimentation, investigation, observation, etc.*

Since their inception in [1] over a decade ago now, giant gravitons have matured into one of the best laboratories - if the above definition is anything to go by - that we have for studying the physics of D-branes and, by extension, the open strings that end on them. Indeed, directly or indirectly, giant gravitons have played a significant rôle in many of the biggest advances in string theory over these past ten years. These include (but are by no means limited to):

- i) the realization that D-branes are not described in the dual $SU(N)$ super-Yang-Mills theory by *single-trace* operators but rather by *determinant-like* operators whose \mathcal{R} -charge is $\sim \mathcal{O}(N)$. For the case of (excited) giant gravitons, these operators are known exactly. They are (restricted) Schur polynomials, $\chi_R(\Phi) = \frac{1}{n!} \sum_{\sigma \in \mathcal{S}_n} \chi_R(\sigma) \text{tr}(\sigma \Phi^{\otimes n})$, built from fields in the Yang-Mills supermultiplet and labeled by Young diagrams with $n \sim \mathcal{O}(N)$ boxes,
- ii) a complete classification all $\frac{1}{2}$ -BPS geometries of type IIB supergravity in [2] based on the free fermion description of giant graviton states given in [3, 4],
- iii) a detailed understanding of the structure of open string integrability in string theory as developed in [5] and the corresponding statements about the integrability of $\mathcal{N} = 4$ super Yang-Mills theory to be found in [6]. Indeed, so powerful are the tools developed from giant graviton operators [7] that they have recently even opened the door to the study of integrability beyond the planar level in the gauge theory [8] and,

- iv) a concrete proposal for the realization of the idea that quantum gravity and spacetime itself are emergent phenomena [9] (see also [10] for a summary of these ideas) encoded in the quantum interactions of a matrix model.

It is this last research program that will be of most relevance to us in this article. The idea that spacetime, its local (geometrical) and global (topological) properties are not fundamental but emerge in some “coarse-graining” limit of quantum gravity is not a new one and is certainly not unique to string theory. What string theory does bring to the table though is a concrete way to take such a limit via the AdS/CFT correspondence [11]. Broadly speaking, this gauge/gravity duality says that in the large N limit, certain gauge theories (like 4-dimensional $\mathcal{N} = 4$, $SU(N)$ super Yang-Mills theory) behave more like gravity than gauge theories (and vice versa). It is in this sense that, in the AdS/CFT context, spacetime is *emergent*. This then begs the question:

How is the geometry and topology of bulk physics encoded in the gauge theory?

Recent advances in Schur operator technology, starting with [3, 12] and more recently developed in the series of articles [7], have facilitated enormous strides toward answering these questions. For instance, it was convincingly argued in [13], and later verified in great detail in [7], that the fact that the giant graviton worldvolume is a compact space is encoded in the combinatorics of the Young diagrams that label the associated Schur operators. More precisely, any closed hypersurface (like the D3-brane worldvolume) must satisfy Gauss’ law, thereby constraining how open strings may be attached to the D-brane. In the gauge theory, attaching open strings translates into adding a word of length $\sim \mathcal{O}(\sqrt{N})$ to the Schur polynomial corresponding to the giant or, equivalently, adding a box to a Young diagram. The Littlewood-Richardson rules that govern such additions precisely reproduce Gauss’ law and consequently the topology of the spherical giant.

Geometry on the other hand is a *local* property of spacetime and if, as asserted by the gauge/gravity correspondence, the bulk spacetime and boundary gauge theory describe exactly the same physics with a different organization of degrees of freedom, this locality should also manifest on the boundary. In the first systematic study of this question, it was demonstrated - through a combinatorial tour de force - in [14] that the *shape* of a spherical D3-brane giant graviton can be read off from the spectrum of one loop anomalous dimensions of excitations of subdeterminant operators of the form $\mathcal{O}_{|D3}^{N-k} = \epsilon^{\mu_1 \dots \mu_N} \epsilon_{\rho_1 \dots \rho_N} \Phi_{\mu_1}^{\rho_1} \dots \Phi_{\mu_{N-k}}^{\rho_{N-k}} \delta_{\mu_{N-k+1}}^{\rho_{N-k+1}} \dots \delta_{\mu_N}^{\rho_N}$. Such excited operators are constructed by replacing one (or more) of the δ ’s with one (or more) words of the form Z^n . However, the combinatorics of these operators is, to say the least, formidable and the results obtained in [14] were restricted to *near maximal* sized giants. Here too, once it was realized that Schur polynomials (and their restrictions) furnish a

more complete basis for giant graviton operators (and their excitations) [3, 7, 12], rapid progress was made on many outstanding problems. These include:

- i) Verification of the results reported in [14] and an extension (a) beyond the near-maximal giant and (b) to multiple strings attached to the D-brane worldvolume together with a dynamical mechanism for the emergence of the Chan-Paton factors for open strings propagating on multiple membranes [7].
- ii) A concrete construction of new $\frac{1}{2}$ -BPS geometries [15] from coherent states of gravitons propagating on $AdS_5 \times S^5$ through the study of Schur polynomials with large \mathcal{R} -charge $\Delta \sim \mathcal{O}(N^2)$ and even,
- iii) A proposal for a mechanism of the emergence of the thermodynamic properties of gravity in the presence of horizons, again through an analysis of heavy states with conformal dimension $\sim \mathcal{O}(N^2)$ in the dual gauge theory [16, 17].

All in all, it is fair to say that the program to understand the emergence of spacetime in AdS/CFT has met with some success. Nevertheless, there remains much to do. Of the problems that remain, probably the most pressing is the question of how far beyond the $\frac{1}{2}$ -BPS sector these results extend. This is, however, also one of the most difficult problems since, by definition, we would expect to lose much of the protection of supersymmetry and the powerful non-renormalization theorems that accompany it.

On a more pragmatic level, one could well argue that the claim that spacetime geometry and topology are emergent properties of the gauge theory at large N would be more convincing if said geometries and topologies were more, well, interesting than just the sphere¹. For example, showing that Gauss' law is encoded in the combinatorics of the Young diagrams that label the Schur polynomials is an excellent step forward, but since it is a condition that must be satisfied by *any* compact worldvolume, by itself it is not a good characterization of topology. An obvious next step would be to understand how a topological invariant such as *genus* is encoded in the gauge theory. The problem is that topologically and geometrically nontrivial giant graviton configurations are like the proverbial needle in the haystack: few and far between. More to the point, until very recently, there were no candidate dual operators to these giants in the literature.

The turnaround in this state of affairs came with the discovery of a new example of the AdS/CFT duality, this time between the type IIA superstring on $AdS_4 \times \mathbb{CP}^3$ and an $\mathcal{N} = 6$, super Chern-Simons theory on the 3-dimensional boundary of the

¹Although even a cursory glance at any of [7, 12] would be enough to convince the reader that there's nothing trivial about recovering the spherical geometry.

AdS space - the so-called ABJM model [18, 19]. While this new AdS_4/CFT_3 duality shares much in common with its more well-known and better understood higher dimensional counterpart (a well-defined perturbative expansion, integrability etc.), it is also sufficiently different that the hope that it will provide just as invaluable a testing ground as AdS_5/CFT_4 is not without justification. In particular, in a recent study of membranes in M-theory and their IIA decendants [20], a new class of giant gravitons with large angular momentum and a D0-brane charge was discovered with a toroidal worldvolume. More importantly, with the gauge theory in this case nearly as controlled as $\mathcal{N} = 4$ super Yang-Mills theory, a class of $\frac{1}{2}$ -BPS monopole operators has been mooted as the candidate duals to these giant torii in [21] by matching the energy of the quadratic fluctuations about the monopole configuration to that of the giant graviton. Of course, matching energies is a little like a “3-sigma” event at a collider experiment: while nobody’s booking tickets to Stockholm yet, it certainly points to something interesting going on. Much more work needs to be done to show how the full torus is recovered in the field theory.

The situation is just as intriguing with respect to geometry. It is by now well known that giant gravitons on $AdS_5 \times S^5$ come in two forms: both are spheres (one extended in the AdS space and one in the S^5), both are D3-branes and each is the Hodge dual of the other. Similarly, giant gravitons on $AdS_4 \times \mathbb{CP}^3$ are expected to come in two forms also. The D2-brane “AdS” giant graviton was constructed in [20, 22]. This expands on the 2-sphere in AdS_4 , is perturbatively stable and, apart from a non-vanishing coupling between the worldvolume gauge fields and the transverse fluctuations, exhibits a spectrum similar to that of the giant in AdS_5 . The dual to this configuration - a D4-brane giant graviton wrapping some trivial cycle in the \mathbb{CP}^3 - has proven to be much more difficult to construct. This is due in no small part to its highly non-trivial geometry [23] and it is precisely this geometry, and the possibility of seeing it encoded in the ABJM gauge theory, that makes this giant so interesting.

In this article we take the first steps toward extracting this geometry by constructing the D4-brane giant graviton in the type IIA string theory and studying its spectrum of small fluctuations. Our construction follows the methods developed in [24, 25] for the giant graviton on $AdS_5 \times T^{1,1}$ (and later extended to the maximal giant graviton² on $AdS_4 \times \mathbb{CP}^3$ by two of us in [26]). By way of summary, guided by the structure of Schur polynomials in the ABJM model (see Section 2), we formulate an ansatz for the D4-brane giant graviton and show that this solution minimizes the energy of the brane. We are also able to show how the giant grows with increasing momentum until, at maximal size, it “factorizes” into two dibaryons, in excellent agreement with the factorization of the associated subdeterminant operator in the gauge theory.

²See also the recent works [27, 28, 29] for an independent analysis of the maximal giant graviton.

2. Schurs and subdeterminants in ABJM theory

Introduction to the ABJM model

The ABJM model [18] is an $\mathcal{N} = 6$ super Chern-Simons (SCS)-matter theory in 2+1-dimensions with a $U(N)_k \times U(N)_{-k}$ gauge group, and opposite level numbers k and $-k$. Aside from the gauge fields A_μ and \hat{A}_μ , there are two sets of two chiral multiplets $(A_i, \psi_\alpha^{A_i})$ and $(B_i, \psi_\alpha^{B_i})$, corresponding to the chiral superfields \mathcal{A}_i and \mathcal{B}_i in $\mathcal{N} = 2$ superspace, which transform in the (N, \bar{N}) and (\bar{N}, N) bifundamental representations respectively.

The ABJM superpotential takes the form

$$\mathcal{W} = \frac{2\pi}{k} \epsilon^{ij} \epsilon^{kl} \text{tr}(\mathcal{A}_i \mathcal{B}_j \mathcal{A}_k \mathcal{B}_l), \quad (2.1)$$

which exhibits an explicit $SU(2)_A \times SU(2)_B$ \mathcal{R} -symmetry - the two $SU(2)$'s act on the doublets (A_1, A_2) and (B_1, B_2) respectively. There is also an additional $SU(2)_{\mathcal{R}}$ symmetry, under which (A_1, B_2^\dagger) and (A_2, B_1^\dagger) transform as doublets, which enhances the symmetry group to $SU(4)_{\mathcal{R}}$ [30].

The scalar fields can be arranged into the multiplet $Y^a = (A_1, A_2, B_1^\dagger, B_2^\dagger)$, which transforms in the fundamental representation of $SU(4)_{\mathcal{R}}$, with hermitean conjugate $Y_a^\dagger = (A_1^\dagger, A_2^\dagger, B_1, B_2)$. The ABJM action can then be written as [30, 38]

$$\begin{aligned} S = \frac{k}{4\pi} \int d^3x \text{tr} \left\{ \epsilon^{\mu\nu\lambda} \left(A_\mu \partial_\nu A_\lambda + \frac{2i}{3} A_\mu A_\nu A_\lambda - \hat{A}_\mu \partial_\nu \hat{A}_\lambda - \frac{2i}{3} \hat{A}_\mu \hat{A}_\nu \hat{A}_\lambda \right) \right. \\ \left. + D_\mu^\dagger Y_a^\dagger D^\mu Y^a + \frac{1}{12} Y^a Y_a^\dagger Y^b Y_b^\dagger Y^c Y_c^\dagger + \frac{1}{12} Y^a Y_b^\dagger Y^b Y_c^\dagger Y^c Y_a^\dagger \right. \\ \left. - \frac{1}{2} Y^a Y_a^\dagger Y^b Y_c^\dagger Y^c Y_b^\dagger + \frac{1}{3} Y^a Y_b^\dagger Y^c Y_a^\dagger Y^b Y_c^\dagger + \text{fermions} \right\}, \quad (2.2) \end{aligned}$$

where the covariant derivatives are defined as $D_\mu Y^a \equiv \partial_\mu Y^a + i A_\mu Y^a - i Y^a \hat{A}_\mu$ and $D_\mu^\dagger Y_a^\dagger \equiv \partial_\mu Y_a^\dagger - i A_\mu Y_a^\dagger + i Y_a^\dagger \hat{A}_\mu$. There are no kinetic terms associated with the gauge fields - they are dynamic degrees of freedom only by virtue of their coupling to matter.

The two-point correlation function for the free scalar fields in ABJM theory is³

$$\langle (Y^a)^\alpha{}_\gamma(x_1) (Y_b^\dagger)^\beta{}_\epsilon(x_2) \rangle = \frac{\delta_\beta^\alpha \delta_\gamma^\epsilon \delta_b^a}{|x_1 - x_2|}. \quad (2.3)$$

Note that the expression $|x_1 - x_2|$ in the denominator is raised to the power of 2Δ with $\Delta = \frac{1}{2}$ the conformal dimension of the ABJM scalar fields.

³This two-point correlation function is the same as that quoted in [32] up to an overall $\frac{1}{4\pi}$ normalization.

Schur polynomials and subdeterminants

Schur polynomials and subdeterminant operators in the ABJM model cannot be constructed from individual scalar fields, as they are in the canonical case of $\mathcal{N} = 4$ super Yang-Mills (SYM) theory [3, 12], since these fields are in the bifundamental representation of the gauge group and therefore carry indices in *different* $U(N)$'s, which cannot be contracted. However, it is possible, instead, to make use of composite scalar fields of the form⁴

$$(Y^a Y_b^\dagger)_\beta^\alpha = (Y^a)^\alpha_\gamma (Y_b^\dagger)_\beta^\gamma, \quad \text{with } a \neq b, \quad (2.4)$$

which carry indices in the *same* $U(N)$. We shall make use of the composite scalar field $Y^1 Y_3^\dagger = A_1 B_1$ for definiteness.

Let us construct the Schur polynomial $\chi_R(A_1 B_1)$ of length n , with R an irreducible representation of the permutation group S_n , which is labeled by a Young diagram with n boxes:

$$\begin{aligned} \chi_R(A_1 B_1) &= \frac{1}{n!} \sum_{\sigma \in S_n} \chi_R(\sigma) \text{Tr} \{ \sigma(A_1 B_1) \}, \\ \text{with } \text{Tr} \{ \sigma(A_1 B_1) \} &\equiv (A_1 B_1)_{\alpha_{\sigma(1)}}^{\alpha_1} (A_1 B_1)_{\alpha_{\sigma(2)}}^{\alpha_2} \dots (A_1 B_1)_{\alpha_{\sigma(n)}}^{\alpha_n}. \end{aligned} \quad (2.5)$$

This Schur polynomial is the character of $A_1 B_1$ in the irreducible representation R of the unitary group $U(N)$ associated with the same Young diagram via the Schur-Weyl duality.

It was shown in [33], that by writing this Schur polynomials in terms of two separate permutations of the A_1 's and B_1 's:

$$\begin{aligned} \chi_R(A_1 B_1) &= \frac{d_R}{(n!)^2} \sum_{\sigma, \rho \in S_n} \chi_R(\sigma) \chi_R(\rho) \text{Tr} \{ \sigma(A_1) \rho(B_1) \}, \\ \text{with } \text{Tr} \{ \sigma(A_1) \rho(B_1) \} &\equiv (A_1)_{\beta_{\sigma(1)}}^{\alpha_1} \dots (A_1)_{\beta_{\sigma(n)}}^{\alpha_n} (B_1)_{\alpha_{\rho(1)}}^{\beta_1} \dots (B_1)_{\alpha_{\rho(n)}}^{\beta_n}, \end{aligned} \quad (2.6)$$

the two point correlation function takes the form

$$\langle \chi_R(A_1 B_1)(x_1) \chi_S^\dagger(A_1 B_1)(x_2) \rangle = \frac{(f_R)^2 \delta_{RS}}{(x_1 - x_2)^{2n}} \quad \text{with } f_R \equiv \frac{D_R n!}{d_R}. \quad (2.7)$$

Here D_R and d_R are the dimensions of the irreducible representations R of the unitary group $U(N)$ and the permutation group S_n respectively. The two factors of f_R are a result of the fact that two permutations are now necessary to treat the scalar fields A_1 and B_1 in the composite scalar field $A_1 B_1$ separately⁵.

⁴Operators constructed from the composite scalar fields $A_1 A_1^\dagger$, $A_2 A_2^\dagger$, $B_1^\dagger B_1$ or $B_2^\dagger B_2$ must be non-BPS as their conformal dimension cannot equal their \mathcal{R} -charge, which is zero.

⁵We would like to thank the anonymous referee for pointing out a flaw in our original argument.

These Schur polynomials are therefore orthogonal with respect to two-point correlation function in free ABJM theory [33]. They are also $\frac{1}{2}$ -BPS and have conformal dimension $\Delta = n$ equal to their \mathcal{R} -charge. Normalised Schurs $(f_R)^{-1} \chi_R(A_1 B_1)$ therefore form an orthonormal basis for this $\frac{1}{2}$ -BPS sector of ABJM theory.

We shall focus on the special class of Schur polynomials associated with the totally anti-symmetric representation of the permutation group S_n (labeled by a single column with n boxes). These are proportional to subdeterminant operators:

$$\chi_{\square}(A_1 B_1) \propto \mathcal{O}_n^{\text{subdet}}(A_1 B_1) = \frac{1}{n!} \epsilon_{\alpha_1 \dots \alpha_n \alpha_{n+1} \dots \alpha_N} \epsilon^{\beta_1 \dots \beta_n \alpha_{n+1} \dots \alpha_N} (A_1 B_1)_{\beta_1}^{\alpha_1} \dots (A_1 B_1)_{\beta_n}^{\alpha_n} \cdot \square \quad (2.8)$$

As a result of the composite nature of the scalar fields from which they are constructed, these subdeterminants in ABJM theory factorize at maximum size $n = N$ into the product of two full determinant operators

$$\mathcal{O}_N^{\text{subdet}}(A_1 B_1) = (\det A_1) (\det B_1), \quad (2.9)$$

with

$$\det A_1 \equiv \frac{1}{N!} \epsilon_{\alpha_1 \dots \alpha_N} \epsilon^{\beta_1 \dots \beta_N} (A_1)_{\beta_1}^{\alpha_1} \dots (A_1)_{\beta_N}^{\alpha_N} \quad (2.10)$$

$$\det B_1 \equiv \frac{1}{N!} \epsilon^{\alpha_1 \dots \alpha_N} \epsilon_{\beta_1 \dots \beta_N} (B_1)_{\alpha_1}^{\beta_1} \dots (B_1)_{\alpha_N}^{\beta_N}, \quad (2.11)$$

which are varieties of ABJM dibaryons.

This subdeterminant operator $\mathcal{O}_n^{\text{subdet}}(A_1 B_1)$ is dual to a D4-brane giant graviton, extended and moving on the complex projective space $\mathbb{C}\mathbb{P}^3$. The fact that it has a maximum size is merely a consequence of the compact nature of the space in which it lives. We expect the worldvolume of the giant graviton to pinch off as its size increases, until it factorizes into two distinct D4-branes, each of which wraps a holomorphic cycle $\mathbb{C}\mathbb{P}^2 \subset \mathbb{C}\mathbb{P}^3$ (they intersect on a $\mathbb{C}\mathbb{P}^1$). These are dual to full determinant operators (see [26, 27] for a description of dibaryons and the dual topologically stable D4-brane configurations).

3. A point particle rotating on $\mathbb{C}\mathbb{P}^3$

The type IIA $AdS_4 \times \mathbb{C}\mathbb{P}^3$ background spacetime and our parametrization of the complex projective space are described in detail in Appendix A. Let us consider a point particle with mass M moving along the $\chi(t) \equiv \frac{1}{2}(\psi + \phi_1 + \phi_2)$ fibre direction in the complex projective space (a similar system was discussed in [34]). The induced

metric on the worldline of the particle (situated at the centre of the AdS_4 space) can be obtained from the metric (A.1) by setting $r = 0$ and also $\psi(t) = 2\chi(t) + \phi_1 + \phi_2$ with ζ , θ_i and ϕ_i all constant. Hence the induced metric takes the form

$$ds^2 = -R^2 \{1 - \dot{\chi}^2 \sin^2(2\zeta)\} dt^2. \quad (3.1)$$

The action of the point particle is given by

$$S_{\text{particle}}^{\text{point}} = -M \int \sqrt{|ds^2|} = \int dt L \quad \text{with} \quad L = -MR \sqrt{1 - \dot{\chi}^2 \sin^2(2\zeta)}, \quad (3.2)$$

which is dependent on the constant value of ζ at which the particle is positioned. The conserved momentum associated with the angular coordinate χ is

$$P_\chi = \frac{MR \dot{\chi}}{\sqrt{1 - \dot{\chi}^2 \sin^2(2\zeta)}} \quad \implies \quad \dot{\chi} = \frac{P_\chi}{\sin(2\zeta) \sqrt{P_\chi^2 + M^2 R^2 \sin^2(2\zeta)}}, \quad (3.3)$$

from which it is possible to determine the energy $H = P_\chi \dot{\chi} - L$ of the point particle as a function of the momentum P_χ :

$$H = \frac{1}{\sin(2\zeta)} \sqrt{P_\chi^2 + M^2 R^2 \sin^2(2\zeta)}. \quad (3.4)$$

This energy attains its minimum value $H = \sqrt{P_\chi^2 + M^2 R^2}$ when $\zeta = \frac{\pi}{4}$. The point graviton is associated with the massless limit $M \rightarrow 0$ in which the energy H becomes equal to its angular momentum P_χ , indicating a BPS state.

4. The \mathbb{CP}^3 giant graviton

We may associate the four homogeneous coordinates z^a of \mathbb{CP}^3 with the ABJM scalar fields in the multiplet $Y^a = (A_1, A_2, \bar{B}_1, \bar{B}_2)$. Using the parameterization (A.3), the composite scalar fields $A_i B_j$ are therefore dual to

$$z^1 \bar{z}^3 = \frac{1}{2} \sin(2\zeta) \sin \frac{\theta_1}{2} \sin \frac{\theta_2}{2} e^{\frac{1}{2}i(\psi - \phi_1 - \phi_2)} \quad \longrightarrow \quad A_1 B_1 \quad (4.1)$$

$$z^2 \bar{z}^4 = \frac{1}{2} \sin(2\zeta) \cos \frac{\theta_1}{2} \cos \frac{\theta_2}{2} e^{\frac{1}{2}i(\psi + \phi_1 + \phi_2)} \quad \longrightarrow \quad A_2 B_2 \quad (4.2)$$

$$z^2 \bar{z}^3 = \frac{1}{2} \sin(2\zeta) \cos \frac{\theta_1}{2} \sin \frac{\theta_2}{2} e^{\frac{1}{2}i(\psi + \phi_1 - \phi_2)} \quad \longrightarrow \quad A_2 B_1 \quad (4.3)$$

$$z^1 \bar{z}^4 = \frac{1}{2} \sin(2\zeta) \sin \frac{\theta_1}{2} \cos \frac{\theta_2}{2} e^{\frac{1}{2}i(\psi - \phi_1 + \phi_2)} \quad \longrightarrow \quad A_1 B_2. \quad (4.4)$$

Aside from the additional factor of $\frac{1}{2} \sin(2\zeta)$, these combinations bear an obvious resemblance to the parameterization [35] of the base manifold $T^{1,1}$ of a cone \mathcal{C} in \mathbb{C}^4 . We may therefore adapt the ansatz of [24, 25], which describes a D3-brane giant graviton on $AdS_5 \times T^{1,1}$, to construct a D4-brane giant graviton on $AdS_4 \times \mathbb{CP}^3$.

4.1 Giant graviton ansatz

Our ansatz for a D4-brane giant graviton on $AdS_4 \times \mathbb{CP}^3$, which is positioned at the centre of the anti-de Sitter space, takes the form

$$\sin(2\zeta) \sin \frac{\theta_1}{2} \sin \frac{\theta_2}{2} = \sqrt{1 - \alpha^2}, \quad (4.5)$$

where the constant $\alpha \in [0, 1]$ describes the size of the giant. Motion is along the angular direction $\chi \equiv \frac{1}{2}(\psi - \phi_1 - \phi_2)$, as in the case of the D2-brane dual giant graviton on $AdS_4 \times \mathbb{CP}^3$ studied in [22]. This is also analogous to the direction of motion of the giant graviton [24, 25] on $AdS_5 \times T^{1,1}$, up to a constant multiple, which we have included to account for the difference between the conformal dimensions of the scalar fields in Klebanov-Witten and ABJM theory.

Since this giant graviton is extended and moving on the complex projective space, it is confined to the background $\mathbb{R} \times \mathbb{CP}^3$ with metric

$$ds^2 = R^2 \{ -dt^2 + ds_{\text{radial}}^2 + ds_{\text{angular}}^2 \}, \quad (4.6)$$

where the radial and angular parts of the metric are given by

$$ds_{\text{radial}}^2 = 4 d\zeta^2 + \cos^2 \zeta d\theta_1^2 + \sin^2 \zeta d\theta_2^2 \quad (4.7)$$

$$ds_{\text{angular}}^2 = \cos^2 \zeta \sin^2 \zeta [d\psi + \cos \theta_1 d\phi_1 + \cos \theta_2 d\phi_2]^2 + \cos^2 \zeta \sin^2 \theta_1 d\phi_1^2 + \sin^2 \zeta \sin^2 \theta_2 d\phi_2^2. \quad (4.8)$$

Only the 2-form and 6-form field strengths (A.5) and (A.7) remain non-trivial.

Let us now define new sets of radial coordinates $z_i \equiv \cos^2 \frac{\theta_i}{2}$ and $y \equiv \cos(2\zeta)$, and angular coordinates $\chi \equiv \frac{1}{2}(\psi - \phi_1 - \phi_2)$ and $\varphi_i \equiv \phi_i$ in terms of which the radial and angular metrics can be written as follows:

$$ds_{\text{radial}}^2 = \frac{dy^2}{(1-y^2)} + \frac{1}{2}(1+y) \frac{dz_1^2}{z_1(1-z_1)} + \frac{1}{2}(1-y) \frac{dz_2^2}{z_2(1-z_2)} \quad (4.9)$$

$$ds_{\text{angular}}^2 = (1-y^2) [d\chi + z_1 d\varphi_1 + z_2 d\varphi_2]^2 + 2(1+y) z_1(1-z_1) d\varphi_1^2 + 2(1-y) z_2(1-z_2) d\varphi_2^2. \quad (4.10)$$

The constant dilaton still satisfies $e^{2\Phi} = \frac{4R^2}{k^2}$, while the non-trivial field strength forms on $\mathbb{R} \times \mathbb{CP}^3$ are given by

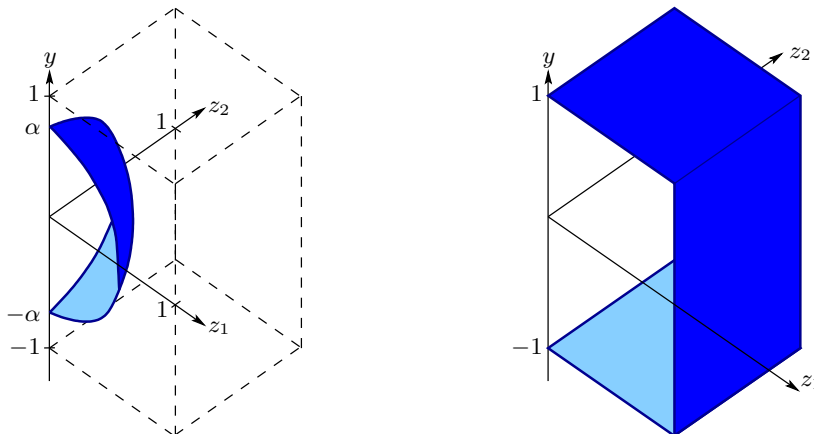
$$F_2 = \frac{1}{2}k \{ dy \wedge [d\chi + z_1 d\varphi_1 + z_2 d\varphi_2] + (1+y) dz_1 \wedge d\varphi_1 - (1-y) dz_2 \wedge d\varphi_2 \} \quad (4.11)$$

$$F_6 = \frac{3}{2}kR^4 (1-y^2) dy \wedge dz_1 \wedge dz_2 \wedge d\chi \wedge d\varphi_1 \wedge d\varphi_2. \quad (4.12)$$

Our giant graviton ansatz

$$(1 - y^2)(1 - z_1)(1 - z_2) = 1 - \alpha^2 \quad (4.13)$$

describes a surface in 3D radial (y, z_1, z_2) space. (Horizontal slices parallel to the $z_1 z_2$ -plane, at fixed $y \in [-\alpha, \alpha]$, are shifted hyperbolae.) The maximal giant graviton $\alpha = 1$ can be viewed as part of a rectangular box with sides $z_1 = 1$, $z_2 = 1$ and $y = \pm 1$. Note that the top and bottom sides $y = \pm 1$ result in coordinate singularities⁶ and therefore yield no contribution to the worldvolume of the maximal giant graviton.



(a) Submaximal giant graviton $0 < \alpha < 1$ (b) Maximal giant graviton $\alpha = 1$

Figure 1: A sketch of the submaximal and maximal \mathbb{CP}^3 giants in radial (y, z_1, z_2) space.

This ansatz for the giant graviton on $AdS_4 \times \mathbb{CP}^3$ is similar to the ansatz [25] for the giant graviton on $AdS_5 \times T^{1,1}$. The 5-dimensional compact space $T^{1,1}$, in which this D3-brane is embedded, consists of two 2-spheres and a non-trivial $U(1)$ fibre - motion is along the fibre direction. In the case of our D4-brane giant embedded in the 6-dimensional compact space \mathbb{CP}^3 , there is an additional radial coordinate y , which controls the (now variable) related sizes of the two 2-spheres in the complex projective space. In both cases, the giant graviton splits up into two pieces at maximal size.

To obtain both halves of the maximal giant graviton as a limiting case $\alpha \rightarrow 1$ of the submaximal giant graviton, we could parameterize the two regions $z_1 \leq z_2$ and $z_1 \geq z_2$ separately. Note that, as result of the symmetry of the problem, these would yield identical contributions to the D4-brane action. However, for convenience, we shall simply parameterize the full worldvolume of the submaximal giant graviton using the coordinates $\sigma^a = (t, y, z_1, \varphi_1, \varphi_2)$ with ranges

$$y \in [-\alpha, \alpha], \quad z_1 \in \left[0, \frac{\alpha^2 - y^2}{1 - y^2}\right] \quad \text{and} \quad \varphi_i \in [0, 2\pi]. \quad (4.14)$$

⁶When $y = 1$ (or $y = -1$) all dependence on the second 2-sphere (or first 2-sphere) disappears.

4.2 D4-brane action

The D4-brane action $S_{D4} = S_{\text{DBI}} + S_{\text{WZ}}$, which describes the dynamics of our giant graviton, consists of Dirac-Born-Infeld (DBI) and Wess-Zumino (WZ) terms:

$$S_{\text{DBI}} = -T_4 \int_{\Sigma} d^5\sigma e^{-\Phi} \sqrt{-\det(\mathcal{P}[g] + 2\pi F)}, \quad (4.15)$$

and

$$S_{\text{WZ}} = \pm T_4 \int_{\Sigma} \left\{ \mathcal{P}[C_5] + \mathcal{P}[C_3] \wedge (2\pi F) + \frac{1}{2} \mathcal{P}[C_1] \wedge (2\pi F) \wedge (2\pi F) \right\}, \quad (4.16)$$

with $T_4 \equiv \frac{1}{(2\pi)^4}$ the tension. Here we have included the possibility of a non-trivial worldvolume gauge field F . Since the form field C_3 has components only in AdS_4 , the corresponding term in the WZ action vanishes when pulled-back to the worldvolume Σ of the giant graviton - an object extended only in \mathbb{CP}^3 .

Now, it is consistent (as an additional specification in our giant graviton ansatz) to turn off all worldvolume fluctuations. Note that these should be included when we turn our attention to the spectrum of small fluctuations. Hence the D4-brane action becomes

$$S_{D4} = -T_4 \int_{\Sigma} d^5\sigma e^{-\Phi} \sqrt{-\det(\mathcal{P}[g])} \pm T_4 \int_{\Sigma} \mathcal{P}[C_5]. \quad (4.17)$$

Dirac-Born-Infeld action

The induced radial metric on the worldvolume of the giant graviton can be obtained by setting $z_2(z_1)$ from the constraint (4.5). Hence

$$\begin{aligned} ds_{\text{rad}}^2 &= \frac{[(1-y^2)z_2 + 2y^2(1-y)(1-z_2)]}{2(1-y^2)^2 z_2} dy^2 + \frac{2y(1-y)(1-z_2)}{(1-y^2)(1-z_1)^2 z_2} dy dz_1 \\ &+ \frac{[(1+y)(1-z_1)z_2 + (1-y)z_1(1-z_2)]}{2z_1(1-z_1)^2 z_2} dz_1^2. \end{aligned} \quad (4.18)$$

The determinant in the coordinates (y, z_1) is then given by

$$\det g_{\text{rad}}^{\text{ind}} = \frac{\left[\frac{1}{2}(1+y)(1-z_1) + \frac{1}{2}(1+y)(1-z_2) - (1-\alpha^2) \right]}{z_1(1-z_1)^2 z_2}. \quad (4.19)$$

The temporal and angular part of the induced metric on the worldvolume of the giant graviton takes the form

$$ds_{t, \text{ang}}^2 = -dt^2 + (1-y^2) [\dot{\chi} dt + z_1 d\varphi_1 + z_2 d\varphi_2]^2 + 2z_1(1-z_1) d\varphi_1^2 + 2z_2(1-z_2) d\varphi_2^2,$$

which has the following determinant

$$\begin{aligned}\det g_{t, \text{ang}}^{\text{ind}} &= - \{ (C_{\text{ang}})_{11} - \dot{\chi}^2 [\det g_{\text{ang}}] \} \\ &= -4 (1 - y^2) z_1 z_2 \\ &\quad \times \left\{ \left[\frac{1}{2} (1 + y) (1 - z_1) + \frac{1}{2} (1 + y) (1 - z_2) - (1 - \alpha^2) \right] + (1 - \dot{\chi}^2) (1 - \alpha^2) \right\}.\end{aligned}\tag{4.20}$$

The determinant of the pullback of the metric to the worldvolume of the giant graviton in the coordinates $(t, y, z_1, \varphi_1, \varphi_2)$ is therefore given by

$$\begin{aligned}\det \mathcal{P} [g] &= - \frac{4R^{10}}{(1 - z_1)^2} \left[\frac{1}{2} (1 + y) (1 - z_1) + \frac{1}{2} (1 - y) (1 - z_2) - (1 - \alpha^2) \right]^2 \\ &\quad \times \left\{ 1 + \frac{(1 - \dot{\chi}^2) (1 - \alpha^2)}{\left[\frac{1}{2} (1 + y) (1 - z_1) + \frac{1}{2} (1 - y) (1 - z_2) - (1 - \alpha^2) \right]} \right\},\end{aligned}\tag{4.21}$$

while $e^{-\Phi} = \frac{k}{2R}$. Integrating over φ_1 and φ_2 , we obtain the DBI action

$$S_{\text{DBI}} = \int dt L_{\text{DBI}} \quad \text{with} \quad L_{\text{DBI}} = \int_{-\alpha}^{\alpha} dy \int_0^{\frac{\alpha^2 - y^2}{1 - y^2}} dz_1 \mathcal{L}_{\text{DBI}}(y, z_1)\tag{4.22}$$

associated with the radial DBI Lagrangian density

$$\begin{aligned}\mathcal{L}_{\text{DBI}}(y, z_1) &= - \frac{N}{2} \frac{1}{(1 - z_1)} \left[\frac{1}{2} (1 + y) (1 - z_1) + \frac{1}{2} (1 - y) (1 - z_2) - (1 - \alpha^2) \right] \\ &\quad \times \sqrt{1 + \frac{(1 - \dot{\chi}^2) (1 - \alpha^2)}{\left[\frac{1}{2} (1 + y) (1 - z_1) + \frac{1}{2} (1 - y) (1 - z_2) - (1 - \alpha^2) \right]}},\end{aligned}\tag{4.23}$$

where $z_2(z_1) = 1 - \frac{(1 - \alpha^2)}{(1 - y^2)(1 - z_1)}$ and the ABJM duality associates the rank N of the product gauge group with the flux $N \equiv \frac{kR^4}{2\pi^2}$ of the 6-form field strength through the complex projective space.

Wess-Zumino action

In order to calculate the WZ action, we need to determine the 5-form field C_5 associated with the 6-form field strength $F_6 = dC_5$. (The former is only defined up to an exact form of integration.) Usually we would change to orthogonal radial worldvolume coordinates (α, u, v) and then integrate F_6 on α subject to the condition $C_5(\alpha = 0) = 0$. However, in this case, it is not immediately obvious how to determine u and v , so we must proceed via an alternative route.

Consider the 5-form field

$$\begin{aligned}C_5 &= \frac{1}{2} kR^4 \{ y (1 - y^2) dz_1 \wedge dz_2 - (1 - y) z_1 dy \wedge dz_2 + (1 + y) z_2 dy \wedge dz_1 \} \\ &\quad \wedge d\chi \wedge d\varphi_1 \wedge d\varphi_2,\end{aligned}\tag{4.24}$$

which satisfies both $F_6 = dC_5$ and $C_5(y = z_1 = z_2 = 0) = 0$. When pulled back to the worldvolume of the giant graviton, this becomes

$$\mathcal{P}[C_5] = \frac{kR^4 \dot{\chi}}{(1-z_1)} \left[\frac{1}{2}(1+y)(1-z_1) + \frac{1}{2}(1-y)(1-z_2) - (1-\alpha^2) \right] \quad (4.25)$$

$$dt \wedge dy \wedge dz_1 \wedge d\varphi_1 \wedge d\varphi_2,$$

where $z_2(z_1)$ follows directly from the giant graviton constraint (4.5). The WZ action is therefore given by

$$S_{\text{WZ}} = \int dt L_{\text{WZ}} \quad \text{with} \quad L_{\text{WZ}} = \int_{-\alpha}^{\alpha} dy \int_0^{\frac{\alpha^2-y^2}{1-y^2}} dz_1 \mathcal{L}_{\text{WZ}}(y, z_1), \quad (4.26)$$

with radial WZ Lagrangian density

$$\mathcal{L}_{\text{WZ}}(y, z_1) = \pm \frac{N}{2} \frac{\dot{\chi}}{(1-z_1)} \left[\frac{1}{2}(1+y)(1-z_1) + \frac{1}{2}(1-y)(1-z_2) - (1-\alpha^2) \right], \quad (4.27)$$

where, again, $z_2(z_1) = 1 - \frac{(1-\alpha^2)}{(1-y^2)(1-z_1)}$. The \pm distinguishes between branes and anti-branes. We shall confine our attention to the positive sign, indicative of a D4-brane.

Full D4-brane action

We can combine the DBI and WZ terms in the action to obtain the D4-brane action

$$S_{\text{D4}} = \int dt L_{\text{D4}} \quad \text{with} \quad L_{\text{D4}} = \int_{-\alpha}^{\alpha} dy \int_0^{\frac{\alpha^2-y^2}{1-y^2}} dz_1 \mathcal{L}_{\text{D4}}(y, z_1) \quad (4.28)$$

associated with the radial Lagrangian density

$$\mathcal{L}_{\text{D4}}(y, z_1) = -\frac{N}{2} \frac{1}{(1-z_1)} \left[\frac{1}{2}(1+y)(1-z_1) + \frac{1}{2}(1-y)(1-z_2) - (1-\alpha^2) \right] \quad (4.29)$$

$$\times \left\{ \sqrt{1 + \frac{(1-\dot{\chi}^2)(1-\alpha^2)}{\left[\frac{1}{2}(1+y)(1-z_1) + \frac{1}{2}(1-y)(1-z_2) - (1-\alpha^2) \right]^2}} - \dot{\chi} \right\},$$

where $z_2(z_1) = 1 - \frac{(1-\alpha^2)}{(1-y^2)(1-z_1)}$ and $N \equiv \frac{kR^4}{2\pi^2}$ denotes the flux of the 6-form field strength through the complex projective space.

4.3 Energy and momentum

The conserved momentum conjugate to the coordinate χ takes the form

$$P_{\chi} = \int_{-\alpha}^{\alpha} dy \int_0^{\frac{\alpha^2-y^2}{1-y^2}} dz_1 \mathcal{P}_{\chi}(y, z_1), \quad (4.30)$$

written in terms of the momentum density

$$\mathcal{P}_\chi(y, z_1) = \frac{N}{2} \frac{1}{(1-z_1)} \left[\frac{1}{2} (1+y)(1-z_1) + \frac{1}{2} (1-y)(1-z_2) - (1-\alpha^2) \right] \\ \times \left\{ \frac{\frac{(1-\alpha^2)\dot{\chi}}{\left[\frac{1}{2}(1+y)(1-z_1) + \frac{1}{2}(1-y)(1-z_2) - (1-\alpha^2) \right]}}{\sqrt{1 + \frac{(1-\dot{\chi}^2)(1-\alpha^2)}{\left[\frac{1}{2}(1+y)(1-z_1) + \frac{1}{2}(1-y)(1-z_2) - (1-\alpha^2) \right]}}} + 1 \right\}. \quad (4.31)$$

The energy $H = P_\chi \dot{\chi} - L$ of this D4-brane configuration can hence be determined as a function of its size α and the angular velocity $\dot{\chi}$ as follows:

$$H = \int_{-\alpha}^{\alpha} dy \int_0^{\frac{\alpha^2 - y^2}{1 - y^2}} dz_1 \mathcal{H}(y, z_1) \quad (4.32)$$

with

$$\mathcal{H}(y, z_1) = \frac{N}{2} \frac{1}{(1-z_1)} \frac{\left[\frac{1}{2} (1+y)(1-z_1) + \frac{1}{2} (1-y)(1-z_2) \right]}{\sqrt{1 + \frac{(1-\dot{\chi}^2)(1-\alpha^2)}{\left[\frac{1}{2}(1+y)(1-z_1) + \frac{1}{2}(1-y)(1-z_2) - (1-\alpha^2) \right]}}} \quad (4.33)$$

the Hamiltonian density. Here $z_2(z_1) = 1 - \frac{(1-\alpha^2)}{(1-y^2)(1-z_1)}$ is an implicit function of the worldvolume coordinates y and z_1 , so that we can write $(1-y)(1-z_2) = \frac{1-\alpha^2}{(1+y)(1-z_1)}$, a combination ubiquitous in the above expressions.

Note that the first contribution to the momentum is due to angular motion along the χ direction. At maximal size $\alpha = 1$, the D4-brane is no longer moving and this term vanishes. The momentum is then determined entirely by the second contribution, resulting from the extension of the D4-brane in the complex projective space.

4.4 Giant graviton solution

The task now is to solve for the finite size α_0 giant graviton configuration, which is associated with a minimum in the energy $H(\alpha, P_\chi)$, plotted as a function of α at some fixed momentum P_χ . Unfortunately, inverting $P_\chi(\dot{\chi})$ for $\dot{\chi}(P_\chi)$ analytically and then substituting the result into the energy $H(\alpha, \dot{\chi})$ to obtain $H(\alpha, P_\chi)$ is problematic. We hence resort to the numerical integration of the momentum (4.30) and energy (4.32), as described in Appendix B, to produce the standard energy plots for this D4-brane configuration, which are shown in Figure 2.

The giant graviton solution, visible as the finite size $\alpha = \alpha_0$ minimum in the energy, always occurs when $\dot{\chi} = 1$ and is energetically degenerate with the point graviton

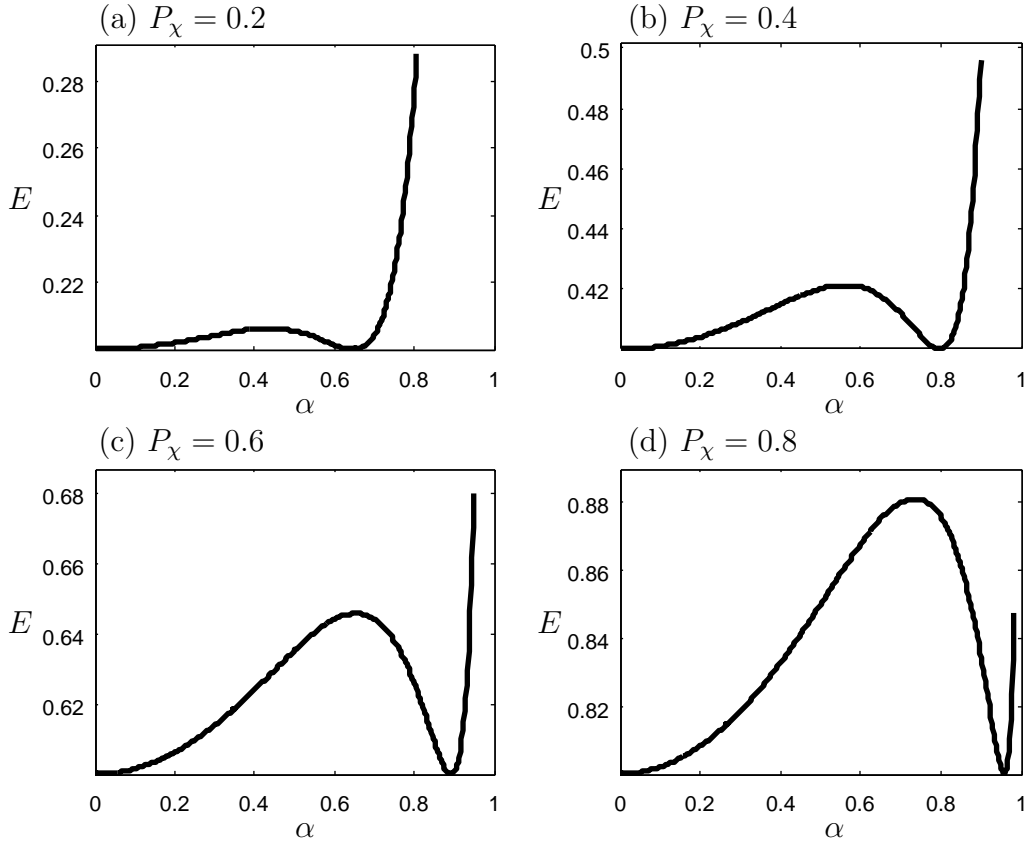


Figure 2: The energy of the D4-brane configuration, plotted as a function of the size α at fixed momentum P_χ , in units of the flux N .

solution at $\alpha = 0$ (previously described in Section 3). Now, substituting $\dot{\chi} = 1$ into the momentum and energy integrals (4.30) and (4.32) respectively, we obtain

$$H = P_\chi = \frac{N}{4} \int_{-\alpha_0}^{\alpha_0} dy \int_0^{\frac{\alpha_0^2 - y^2}{1 - y^2}} dz_1 \left[(1 + y) + \frac{(1 - \alpha_0^2)}{(1 + y)(1 - z_1)^2} \right]. \quad (4.34)$$

This integral is perfectly tractable! The energy and momentum of the submaximal giant graviton solution (plotted in Figure 3) can hence be determined as follows:

$$H = P_\chi = N \left\{ \alpha_0 + \frac{1}{2} (1 - \alpha_0^2) \ln \left(\frac{1 - \alpha_0}{1 + \alpha_0} \right) \right\}, \quad (4.35)$$

which is defined for all $\alpha_0 \in (0, 1)$. Note that the maximal giant graviton limit, in which $\alpha \rightarrow 1$, is well-defined and yields $H = P_\chi = N$ as expected (being twice the energy of a \mathbb{CP}^2 dibaryon [26, 27]).

We have therefore completed our construction of the submaximal giant graviton in type IIA string theory on $AdS_4 \times \mathbb{CP}^3$ - which we refer to as the \mathbb{CP}^3 giant graviton (indicating the space in which the D4-brane is extended, rather than the shape of the object, which changes as the size α_0 increases). We expect this to be a BPS

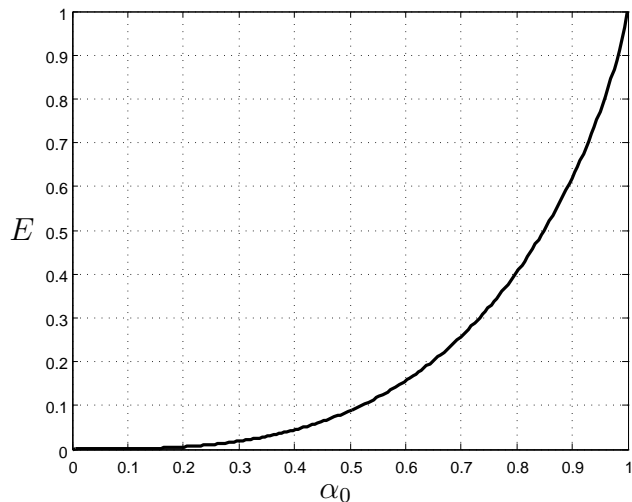


Figure 3: The energy of the giant graviton as a function of its size α_0 (in units of N).

configuration, although we have not yet computed the number of supersymmetries preserved by the Killing-Spinor equations. This is dual to the subdeterminant operator $\mathcal{O}_n(A_1 B_1)$ in ABJM theory. The equality between the energy and momentum P_χ agrees with the fact that the conformal dimension of the subdeterminant $\Delta = n$ is the same as its \mathcal{R} -charge.

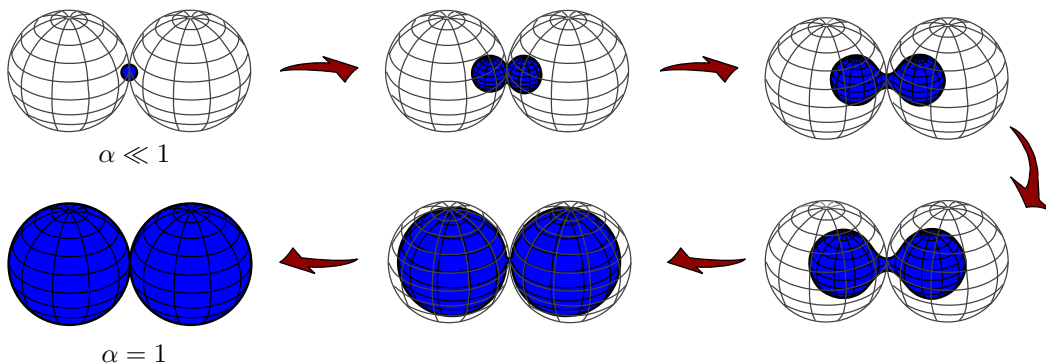


Figure 4: A cartoon representation of the growth of the $\mathbb{C}\mathbb{P}^3$ giant graviton.

In Figure 4 we show a heuristic picture of the growth of the giant graviton in the complex projective space. The small submaximal giant is a nearly spherical configuration, similar in nature to the canonical case. As the size increases, however, its worldvolume pinches off, until it factorizes into two D4-branes, wrapped on different $\mathbb{C}\mathbb{P}^2$ subspaces and intersecting on a $\mathbb{C}\mathbb{P}^1$ (these are the $\mathbb{C}\mathbb{P}^2$ dibaryons of [26, 27]). We thereby observe the factorization of the subdeterminant operators in ABJM theory into two full determinants from the gravitational point of view, which is a direct result of the product nature of the SCS-matter gauge group.

5. Fluctuation analysis

This section contains a general analysis of small fluctuations about the giant graviton on $AdS_4 \times \mathbb{CP}^3$. We obtain the D4-brane action and equations of motion describing this perturbed configuration. Included are both scalar and worldvolume fluctuations - we cannot initially rule out the possibility that these may couple, as in case of the spherical dual giant graviton [20, 22]. Our ultimate goal is to determine whether any dependence on the α_0 , which parameterizes the changing shape and size of the giant, is manifest in the fluctuation spectrum.

5.1 Coordinates of $AdS_4 \times \mathbb{CP}^3$ best suited to the fluctuation analysis

Anti-de Sitter spacetime

The metric (A.1) of the anti-de Sitter spacetime AdS_4 can be rewritten in terms of an alternative set of cartesian coordinates v_k , which are more convenient for the purposes of the fluctuation analysis [36]⁷. Here we define

$$v_1 = r \cos \tilde{\theta}, \quad v_2 = r \sin \tilde{\theta} \cos \tilde{\varphi} \quad \text{and} \quad v_3 = r \sin \tilde{\theta} \sin \tilde{\varphi}, \quad (5.1)$$

in terms of which the AdS_4 metric can be written as

$$ds_{AdS_4}^2 = - \left(1 + \sum_k v_k^2 \right) dt^2 + \sum_{i,j} \left(\delta_{ij} - \frac{v_i v_j}{(1 + \sum_k v_k^2)} \right) dv_i dv_j. \quad (5.2)$$

The 4-form field strength (A.6) becomes

$$F_4 = -\frac{3}{2} k R^2 dt \wedge dv_1 \wedge dv_2 \wedge dv_3, \quad (5.3)$$

which is associated with the 3-form potential

$$C_3 = \frac{1}{2} k R^2 dt \wedge (v_1 dv_2 \wedge dv_3 + v_2 dv_3 \wedge dv_1 + v_3 dv_1 \wedge dv_2). \quad (5.4)$$

Complex projective space

The metric of the complex projective space is given by

$$ds_{\mathbb{CP}^3}^2 = \frac{1}{4} (ds_{\text{radial}}^2 + ds_{\text{angular}}^2), \quad (5.5)$$

⁷The original coordinates r , $\tilde{\theta}$ and $\tilde{\varphi}$ have a coordinate singularity at $r = 0$, which is precisely the position of the D4-brane giant graviton.

where we shall assume the following generic forms for the radial and angular metrics:

$$ds_{\text{radial}}^2 = g_{\alpha\alpha} d\alpha^2 + g_{x_1x_1} dx_1^2 + g_{x_2x_2} dx_2^2 + 2g_{\alpha x_1} d\alpha dx_1 + 2g_{\alpha x_2} d\alpha dx_2 + 2g_{x_1x_2} dx_1 dx_2 \quad (5.6)$$

$$ds_{\text{angular}}^2 = g_{\chi\chi} d\chi^2 + g_{\varphi_1\varphi_1} d\varphi_1^2 + g_{\varphi_2\varphi_2} d\varphi_2^2 + 2g_{\chi\varphi_1} d\chi d\varphi_1 + 2g_{\chi\varphi_2} d\chi d\varphi_2 + 2g_{\varphi_1\varphi_2} d\varphi_1 d\varphi_2 \quad (5.7)$$

in the radial coordinates α , x_1 and x_2 , and the angular coordinates χ , φ_1 and φ_2 .

The 6-form field strength is given by

$$F_6 = \frac{3}{2} k R^4 \sqrt{[\det g_{\text{rad}}] [\det g_{\text{ang}}]} d\alpha \wedge dx_1 \wedge dx_2 \wedge d\chi \wedge d\varphi_1 \wedge d\varphi_2, \quad (5.8)$$

which is associated with the 5-form potential⁸

$$C_5 = \frac{1}{2} \sqrt{(C_{\text{rad}})_{11} [(C_{\text{rad}})_{11} - \det g_{\text{ang}}]} \\ \times \left\{ dx_1 \wedge dx_2 - \frac{(C_{\text{rad}})_{12}}{(C_{\text{rad}})_{11}} d\alpha \wedge dx_1 + \frac{(C_{\text{rad}})_{13}}{(C_{\text{rad}})_{11}} d\alpha \wedge dx_2 \right\} d\chi \wedge d\varphi_1 \wedge d\varphi_2, \quad (5.9)$$

while the 2-form field strength can generically be written in terms of the Kähler form on the complex projective space (A.5).

Note that, throughout this section, we studiously avoid any reference to a particular choice of radial worldvolume coordinates⁹ x_1 and x_2 . We leave the metric components and their cofactors (as well as their derivatives) unspecified. We anticipate that, in the subsequent section, it may be convenient to make use of several different sets of coordinates x_i , each of which is best suited to describe a certain limiting case.

5.2 Fluctuation ansatz

Our ansatz for the scalar fluctuations about the worldvolume of the submaximal \mathbb{CP}^3 giant graviton takes the form

$$v_k(\sigma^a) = \varepsilon \delta v_k(\sigma^a), \quad \alpha(\sigma^a) = \alpha_0 + \varepsilon \delta\alpha(\sigma^a) \quad \text{and} \quad \chi(\sigma^a) = t + \varepsilon \delta\chi(\sigma^a), \quad (5.10)$$

whereas the worldvolume fluctuations can be taken into account by setting

$$F(\sigma^a) = \varepsilon \frac{R^2}{2\pi} \delta F(\sigma^a), \quad (5.11)$$

with ε a small parameter. The dependence of the fluctuations on the worldvolume coordinates $\sigma^a = (t, x_1, x_2, \varphi_1, \varphi_2)$ has been shown here explicitly.

⁸It is not immediately obvious that $F_6 = dC_5$. However, it is possible to check this expression for C_5 in one particular set of radial coordinates (for example, α , y and z_1) and then note that it is invariant under any radial coordinate transformation $(\alpha, x_1, x_2) \rightarrow (\alpha, \tilde{x}_1(\alpha, x_1, x_2), \tilde{x}_2(\alpha, x_1, x_2))$ which keeps α fixed.

⁹Except that we assume x_1 and x_2 have fixed coordinate ranges which are independent of α .

5.3 D4-brane action to second order

We shall now determine the D4-brane action associated with this perturbed \mathbb{CP}^3 giant graviton configuration, keeping terms quadratic in ε .

Dirac-Born Infeld action

The DBI action (4.15) can be simplified to the form

$$S_{\text{DBI}} = -\frac{kR^4}{2(2\pi)^4} \int d^5\sigma \sqrt{-\det(h + \varepsilon \delta\mathcal{F})}, \quad \text{with } \delta\mathcal{F} \equiv (2\pi R^{-2}) \delta F, \quad (5.12)$$

where the components of the (scaled) pullback of the metric $h_{ab} \equiv R^{-2} (\mathcal{P}[g])_{ab}$ to the worldvolume of the perturbed D4-brane can be expanded in orders of ε as follows:

$$\begin{aligned} h_{ab} = & \left\{ - (1 - g_{\chi\chi}) \partial_a t \partial_b t + g_{x_1 x_1} \partial_a x_1 \partial_b x_1 + g_{x_2 x_2} \partial_a x_2 \partial_b x_2 + g_{x_1 x_2} (\partial_a x_1 \partial_b x_2 + \partial_a x_2 \partial_b x_1) \right. \\ & + g_{\varphi_1 \varphi_1} \partial_a \varphi_1 \partial_b \varphi_1 + g_{\varphi_2 \varphi_2} \partial_a \varphi_2 \partial_b \varphi_2 + g_{\chi \varphi_1} (\partial_a t \partial_b \varphi_1 + \partial_a \varphi_1 \partial_b t) \\ & + g_{\chi \varphi_2} (\partial_a t \partial_b \varphi_2 + \partial_a \varphi_2 \partial_b t) + g_{\varphi_1 \varphi_2} (\partial_a \varphi_1 \partial_b \varphi_2 + \partial_a \varphi_2 \partial_b \varphi_1) \left. \right\} \\ & + \varepsilon \left\{ g_{\alpha x_1} [(\partial_a \delta\alpha) \partial_b x_1 + \partial_a x_1 (\partial_b \delta\alpha)] + g_{\alpha x_2} [(\partial_a \delta\alpha) \partial_b x_2 + \partial_a x_2 (\partial_b \delta\alpha)] \right. \\ & + g_{\chi\chi} [\partial_a t (\partial_b \delta\chi) + (\partial_a \delta\chi) \partial_b t] + g_{\chi \varphi_1} [(\partial_a \delta\chi) \partial_b \varphi_1 + \partial_a \varphi_1 (\partial_b \delta\chi)] \\ & + g_{\chi \varphi_2} [(\partial_a \delta\chi) \partial_b \varphi_2 + \partial_a \varphi_2 (\partial_b \delta\chi)] \left. \right\} \\ & + \varepsilon^2 \left\{ - \left(\sum_k \delta v_k^2 \right) \delta_a t \delta_b t + \sum_k (\partial_a \delta v_k) (\partial_b \delta v_k) + g_{\alpha\alpha} (\partial_a \delta\alpha) (\partial_b \delta\alpha) + g_{\chi\chi} (\partial_a \delta\chi) (\partial_b \delta\chi) \right\}. \end{aligned} \quad (5.13)$$

Note that the metric components $g_{\mu\nu}(\alpha, x_1, x_2)$ can also be expanded in orders of ε using $\alpha = \alpha_0 + \varepsilon \delta\alpha$. We shall not write out any of these expansions of the metric or its cofactors until the end - it will then turn out that only certain specific combinations need be determined beyond leading order.

It can be shown that, in the DBI action, the scalar fluctuations δv_k , $\delta\alpha$ and $\delta\chi$, and worldvolume fluctuations $\delta\mathcal{F}_{ab}$ decouple:

$$S_{\text{DBI}} = -\frac{kR^4}{2(2\pi)^2} \left(\int d^5\sigma \left\{ \sqrt{-a_0} \left[1 - \varepsilon a_1 + \frac{1}{2} \varepsilon^2 (a_2 - a_1^2) \right] \right\} + \frac{1}{2} \varepsilon^2 \int_{\Sigma} \delta\mathcal{F} \wedge * \delta\mathcal{F} \right), \quad (5.14)$$

where we have expanded the determinant of the induced metric on the pullback of the perturbed D4-brane worldvolume

$$\det h \approx -a_0 (1 - 2\varepsilon a_1 + \varepsilon^2 a_2) \quad (5.15)$$

in orders of ε . Note that the Hodge dual $*\delta\mathcal{F}$ of the fluctuation $\delta\mathcal{F}$ of the worldvolume field strength form is constructed using the rescaled induced metric h_{ab} on the worldvolume of the original \mathbb{CP}^3 giant graviton.

It now remains for us to find explicit expressions for a_0 , a_1 and a_2 :

$$a_0 = (C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}] \quad (5.16)$$

$$\begin{aligned} a_1 = & \frac{(C_{\text{rad}})_{12}}{(C_{\text{rad}})_{11}} (\partial_{x_1} \delta\alpha) + \frac{(C_{\text{rad}})_{13}}{(C_{\text{rad}})_{11}} (\partial_{x_2} \delta\alpha) + \frac{\det g_{\text{ang}}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \dot{\delta}\chi \\ & + \frac{(C_{\text{ang}})_{12}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} (\partial_{\varphi_1} \delta\chi) + \frac{(C_{\text{ang}})_{13}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} (\partial_{\varphi_2} \delta\chi) \end{aligned} \quad (5.17)$$

$$\begin{aligned} a_2 - a_1^2 = & \sum_k \left\{ (\partial \delta v_k)^2 + \frac{(C_{\text{ang}})_{11}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \delta v_k^2 \right\} \\ & + \frac{\det g_{\text{rad}}}{(C_{\text{rad}})_{11}} (\partial \delta\alpha)^2 + \frac{\det g_{\text{ang}}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} (\partial \delta\chi)^2 \\ & + 2 \frac{(C_{\text{rad}})_{12}}{(C_{\text{rad}})_{11}} \frac{\det g_{\text{ang}}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \left[\dot{\delta}\chi (\partial_{x_1} \delta\alpha) - \dot{\delta}\alpha (\partial_{x_1} \delta\chi) \right] \\ & + 2 \frac{(C_{\text{rad}})_{13}}{(C_{\text{rad}})_{11}} \frac{\det g_{\text{ang}}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \left[\dot{\delta}\chi (\partial_{x_2} \delta\alpha) - \dot{\delta}\alpha (\partial_{x_2} \delta\chi) \right] \\ & + 2 \frac{(C_{\text{rad}})_{12}}{(C_{\text{rad}})_{11}} \frac{(C_{\text{ang}})_{12}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} [(\partial_{\varphi_1} \delta\chi) (\partial_{x_1} \delta\alpha) - (\partial_{\varphi_1} \delta\alpha) (\partial_{x_1} \delta\chi)] \\ & + 2 \frac{(C_{\text{rad}})_{13}}{(C_{\text{rad}})_{11}} \frac{(C_{\text{ang}})_{12}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} [(\partial_{\varphi_1} \delta\chi) (\partial_{x_2} \delta\alpha) - (\partial_{\varphi_1} \delta\alpha) (\partial_{x_2} \delta\chi)] \\ & + 2 \frac{(C_{\text{rad}})_{12}}{(C_{\text{rad}})_{11}} \frac{(C_{\text{ang}})_{13}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} [(\partial_{\varphi_2} \delta\chi) (\partial_{x_1} \delta\alpha) - (\partial_{\varphi_2} \delta\alpha) (\partial_{x_1} \delta\chi)] \\ & + 2 \frac{(C_{\text{rad}})_{13}}{(C_{\text{rad}})_{11}} \frac{(C_{\text{ang}})_{13}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} [(\partial_{\varphi_2} \delta\chi) (\partial_{x_2} \delta\alpha) - (\partial_{\varphi_2} \delta\alpha) (\partial_{x_2} \delta\chi)] \end{aligned} \quad (5.18)$$

in terms of the determinants and cofactors of the radial and angular metrics, with $(\partial f)^2$ the gradient squared of a function f on the worldvolume of the \mathbb{CP}^3 giant graviton (see Appendix C).

Wess-Zumino action

The WZ action (4.16) can be written as

$$S_{\text{WZ}} = \frac{kR^4}{(2\pi)^4} \int_{\Sigma} \left\{ (k^{-1}R^{-4}) \mathcal{P}[C_5] + \frac{1}{2} \varepsilon^2 k^{-1} \mathcal{P}[C_1] \wedge \delta F \wedge \delta F \right\}, \quad (5.19)$$

since $\mathcal{P}[C_3]$ is cubic in ε and hence negligible. Note that, while the pullback of the 5-form potential $\mathcal{P}[C_5]$ must be expanded to quadratic order in ε :

$$(k^{-1}R^{-4}) \mathcal{P}[C_5] = \frac{1}{2} b_0 (1 + \varepsilon b_1 + \varepsilon^2 b_2) dt \wedge dx_1 \wedge dx_2 \wedge d\varphi_1 \wedge d\varphi_2, \quad (5.20)$$

it is only necessary to keep the leading order terms in $\mathcal{P}[C_1]$, which involve no scalar fluctuations. The WZ action then simplifies as follows:

$$S_{\text{WZ}} = \frac{kR^4}{2(2\pi)^4} \left(\int d^5\sigma \{b_0 [1 + \varepsilon b_1 + \varepsilon^2 b_2]\} + \varepsilon^2 \int_{\Sigma} B \wedge \delta\mathcal{F} \wedge \delta\mathcal{F} \right), \quad (5.21)$$

where $B = k^{-1} \mathcal{P}[C_1]$, and the coefficients b_0 , b_1 and b_2 are given by

$$b_0 = \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} = \sqrt{a_0} \quad (5.22)$$

$$b_1 = \dot{\delta\chi} - \frac{(C_{\text{rad}})_{12}}{(C_{\text{rad}})_{11}} (\partial_{x_1} \delta\alpha) - \frac{(C_{\text{rad}})_{13}}{(C_{\text{rad}})_{11}} (\partial_{x_2} \delta\alpha) \quad (5.23)$$

$$b_2 = -\frac{(C_{\text{rad}})_{12}}{(C_{\text{rad}})_{11}} \left[\dot{\delta\chi} (\partial_{x_1} \delta\alpha) - \dot{\delta\alpha} (\partial_{x_1} \delta\chi) \right] - \frac{(C_{\text{rad}})_{13}}{(C_{\text{rad}})_{11}} \left[\dot{\delta\chi} (\partial_{x_2} \delta\alpha) - \dot{\delta\alpha} (\partial_{x_2} \delta\chi) \right]. \quad (5.24)$$

D4-brane action

We can combine the DBI and WZ actions to obtain the D4-brane action describing small fluctuations around the D4-brane giant graviton on $\text{AdS}_4 \times \mathbb{CP}^3$. Contrary to our initial expectations, based on the result of a similar fluctuation analysis for the D2-brane dual giant graviton [22], the scalar fluctuations $\delta\alpha$ and $\delta\chi$ do decouple from the worldvolume fluctuations $\delta\mathcal{F}$. The D4-brane action $S_{\text{D4}} = S_{\text{scalar}} + S_{\text{worldvolume}}$ splits into two parts:

$$S_{\text{scalar}} = -\frac{kR^4}{2(2\pi)^4} \int d^5\sigma \left\{ \sqrt{a_0} \left[-\varepsilon (a_1 + b_1) + \varepsilon^2 \left(\frac{1}{2} (a_2 - a_1^2) - b_2 \right) \right] \right\} \quad (5.25)$$

$$S_{\text{worldvolume}} = -\frac{kR^4}{2(2\pi)^4} \varepsilon^2 \int_{\Sigma} \left\{ \frac{1}{4} \delta\mathcal{F} \wedge * \delta\mathcal{F} - B \wedge \delta\mathcal{F} \wedge \delta\mathcal{F} \right\}, \quad \text{with } \delta\mathcal{F} = d\delta\mathcal{A}, \quad (5.26)$$

which will separately yield the equations of motion for the scalar and worldvolume fluctuations respectively.

Let us focus for the moment on the scalar fluctuations. Note that only $\delta\chi$ derivative terms

$$\begin{aligned} -\varepsilon \sqrt{a_0} (a_1 + b_1) &= -\varepsilon \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \\ &\times \left\{ \frac{(C_{\text{ang}})_{11}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \dot{\delta\chi} + \frac{(C_{\text{ang}})_{12}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} (\delta_{\varphi_1} \delta\chi) \right. \\ &\quad \left. + \frac{(C_{\text{ang}})_{13}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} (\delta_{\varphi_2} \delta\chi) \right\} \end{aligned} \quad (5.27)$$

appear in the first order scalar action. The contributions to the $\delta\alpha$ derivative terms from the DBI and WZ actions cancel out - they are actually only there in these individual actions because we are making use of non-orthogonal radial coordinates.

The above expression still needs to be evaluated at $\alpha = \alpha_0 + \varepsilon \delta\alpha$ and expanded in orders of ε . This expansion will yield both first order terms in the action (which are clearly total derivatives) and additional second order contributions:

$$-\varepsilon \sqrt{a_0} (a_1 + b_1) \approx \varepsilon \{\text{total derivatives}\} + \varepsilon^2 \{\dots 2 \dots\} \quad (5.28)$$

with

$$\begin{aligned} \{\dots 2 \dots\} = & -\partial_\alpha \left\{ \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \frac{(C_{\text{ang}})_{11}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \right\} \delta\alpha \dot{\delta\chi} \\ & -\partial_\alpha \left\{ \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \frac{(C_{\text{ang}})_{12}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \right\} \delta\alpha (\partial_{\varphi_1} \delta\chi) \\ & -\partial_\alpha \left\{ \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \frac{(C_{\text{ang}})_{13}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \right\} \delta\alpha (\partial_{\varphi_2} \delta\chi) \end{aligned} \quad (5.29)$$

where the coefficients are now evaluated at $\alpha = \alpha_0$, the fixed size of the giant.

The manifestly second order term in the scalar action can also be simplified. We shall neglect surface terms and hence obtain

$$\varepsilon^2 \sqrt{a_0} \left[\frac{1}{2} (a_2 - a_1^2) - b_2 \right] = \varepsilon^2 \{\dots 1 \dots\} \quad (5.30)$$

with

$$\begin{aligned} \{\dots 1 \dots\} = & \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \left\{ \frac{1}{2} \sum_k \left[(\partial \delta v_k)^2 + \frac{(C_{\text{ang}})_{11}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \delta v_k^2 \right] \right. \\ & \left. + \frac{1}{2} \frac{[\det g_{\text{rad}}]}{(C_{\text{rad}})_{11}} (\partial \delta\alpha)^2 + \frac{1}{2} \frac{[\det g_{\text{ang}}]}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} (\partial \delta\chi)^2 \right\} \end{aligned} \quad (5.31)$$

$$\begin{aligned} & -\partial_{x_1} \left\{ \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \frac{(C_{\text{rad}})_{12}}{(C_{\text{rad}})_{11}} \frac{(C_{\text{ang}})_{11}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \right\} \delta\alpha \dot{\delta\chi} \\ & -\partial_{x_2} \left\{ \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \frac{(C_{\text{rad}})_{13}}{(C_{\text{rad}})_{11}} \frac{(C_{\text{ang}})_{11}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \right\} \delta\alpha \dot{\delta\chi} \\ & -\partial_{x_1} \left\{ \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \frac{(C_{\text{rad}})_{12}}{(C_{\text{rad}})_{11}} \frac{(C_{\text{ang}})_{12}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \right\} \delta\alpha (\partial_{\varphi_1} \delta\chi) \\ & -\partial_{x_2} \left\{ \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \frac{(C_{\text{rad}})_{13}}{(C_{\text{rad}})_{11}} \frac{(C_{\text{ang}})_{12}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \right\} \delta\alpha (\partial_{\varphi_1} \delta\chi) \\ & -\partial_{x_1} \left\{ \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \frac{(C_{\text{rad}})_{12}}{(C_{\text{rad}})_{11}} \frac{(C_{\text{ang}})_{13}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \right\} \delta\alpha (\partial_{\varphi_2} \delta\chi) \\ & -\partial_{x_2} \left\{ \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \frac{(C_{\text{rad}})_{13}}{(C_{\text{rad}})_{11}} \frac{(C_{\text{ang}})_{13}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \right\} \delta\alpha (\partial_{\varphi_2} \delta\chi) \end{aligned}$$

The scalar action to second order in ε therefore takes the form

$$S_{\text{scalar}} = -\frac{\varepsilon^2 k R^4}{2(2\pi)^4} \int d^5\sigma \mathcal{L}_{\text{scalar}}, \quad (5.32)$$

with $\mathcal{L}_{\text{scalar}} = \{\dots 1 \dots\} + \{\dots 2 \dots\}$ the combination of the two previously defined expressions. We now observe that this scalar Lagrangian density can now be written in the more convenient form

$$\begin{aligned} \mathcal{L}_{\text{scalar}} = & \sqrt{-h} \left\{ \frac{1}{2} \sum_k [(\partial \delta v_k)^2 - h^{tt} \delta v_k^2] + \frac{1}{2} \frac{1}{g_{\text{rad}}^{\alpha\alpha}} (\partial \delta\alpha)^2 + \frac{1}{2} \frac{1}{(g_{\text{ang}}^{\chi\chi} - 1)} (\partial \delta\chi)^2 \right\} \\ & + \frac{1}{2} \partial_i \left[\sqrt{-h} \frac{g_{\text{rad}}^{\alpha i}}{g_{\text{rad}}^{\alpha\alpha}} h^{tb} \right] [\delta\alpha (\partial_b \delta\chi) - \delta\chi (\partial_b \delta\alpha)] \end{aligned} \quad (5.33)$$

and, integrating by parts,

$$\mathcal{L}_{\text{scalar}} = -\frac{1}{2} \sqrt{-h} \{\dots\}, \quad (5.34)$$

with

$$\begin{aligned} \{\dots\} = & \sum_k [(\square \delta v_k) + h^{tt} \delta v_k] \delta v_k \quad (5.35) \\ & + \frac{1}{g_{\text{rad}}^{\alpha\alpha}} \left[(\square \delta\alpha) + g_{\text{rad}}^{\alpha\alpha} \partial_a \left(\frac{1}{g_{\text{rad}}^{\alpha\alpha}} \right) h^{ab} (\partial_b \delta\alpha) - \frac{g_{\text{rad}}^{\alpha\alpha}}{\sqrt{-h}} \partial_i \left(\sqrt{-h} \frac{g_{\text{rad}}^{\alpha i}}{g_{\text{rad}}^{\alpha\alpha}} h^{tb} \right) (\partial_b \delta\chi) \right] \delta\alpha \\ & + \frac{1}{(g_{\text{ang}}^{\chi\chi} - 1)} \left[(\square \delta\chi) + (g_{\text{ang}}^{\chi\chi} - 1) \partial_a \left(\frac{1}{g_{\text{ang}}^{\chi\chi} - 1} \right) h^{ab} (\partial_b \delta\chi) \right. \\ & \quad \left. - \frac{(g_{\text{ang}}^{\chi\chi} - 1)}{\sqrt{-h}} \partial_i \left(\sqrt{-h} \frac{g_{\text{rad}}^{\alpha i}}{g_{\text{rad}}^{\alpha\alpha}} h^{tb} \right) (\partial_b \delta\alpha) \right] \delta\chi, \end{aligned}$$

where i and j run over the radial coordinates α , x_1 and x_2 . We make use of the volume element $\sqrt{-h}$, the inverse metric components h^{ab} and the d'Alembertian \square on the worldvolume of the giant graviton, which are defined in Appendix C. We also need several components of the inverse radial metric

$$g_{\text{rad}}^{\alpha\alpha} = \frac{(C_{\text{rad}})_{11}}{\det g_{\text{rad}}}, \quad g_{\text{rad}}^{\alpha x_1} = \frac{(C_{\text{rad}})_{12}}{\det g_{\text{rad}}} \quad \text{and} \quad g_{\text{rad}}^{\alpha x_2} = \frac{(C_{\text{rad}})_{13}}{\det g_{\text{rad}}}, \quad (5.36)$$

and the first component of the inverse angular metric

$$g_{\text{ang}}^{\chi\chi} = \frac{(C_{\text{ang}})_{11}}{\det g_{\text{ang}}}. \quad (5.37)$$

Once the derivatives with respect to α have been taken, all the above expressions are evaluated at $\alpha = \alpha_0$, the fixed size of the giant graviton.

The equations of motion for the scalar fluctuations are therefore given by

$$(\square \delta v_k) + h^{tt} \delta v_k = 0 \tag{5.38}$$

$$(\square \delta \alpha) + g_{\text{rad}}^{\alpha\alpha} \partial_a \left(\frac{1}{g_{\text{rad}}^{\alpha\alpha}} \right) h^{ab} (\partial_b \delta \alpha) - \frac{g_{\text{rad}}^{\alpha\alpha}}{\sqrt{-h}} \partial_i \left(\sqrt{-h} \frac{g_{\text{rad}}^{\alpha i}}{g_{\text{rad}}^{\alpha\alpha}} h^{tb} \right) (\partial_b \delta \chi) = 0 \tag{5.39}$$

$$(\square \delta \chi) + (g_{\text{ang}}^{\chi\chi} - 1) \partial_a \left(\frac{1}{g_{\text{ang}}^{\chi\chi} - 1} \right) h^{ab} (\partial_b \delta \chi) + \frac{(g_{\text{ang}}^{\chi\chi} - 1)}{\sqrt{-h}} \partial_i \left(\sqrt{-h} \frac{g_{\text{rad}}^{\alpha i}}{g_{\text{rad}}^{\alpha\alpha}} h^{tb} \right) (\partial_b \delta \alpha) = 0. \tag{5.40}$$

The \mathbb{CP}^3 fluctuations $\delta\alpha$ and $\delta\chi$ are clearly coupled. It is not immediately obvious, without making a specific choice for the radial worldvolume coordinates x_1 and x_2 , how to define new \mathbb{CP}^3 fluctuations $\delta\beta_{\pm}$, in terms of a linear combination of $\delta\alpha$ and $\delta\chi$, such that the equations of motion for $\delta\beta_+$ and $\delta\beta_-$ decouple. However, once these equations of motion have been decoupled, the obvious ansätze

$$\delta v_k(t, x_1, x_2, \varphi_1, \varphi_2) = e^{i\omega_k t} e^{im_k \varphi_1} e^{in_k \varphi_2} f_k(x_1, x_2) \tag{5.41}$$

$$\delta \beta_{\pm}(t, x_1, x_2, \varphi_1, \varphi_2) = e^{i\omega_{\pm} t} e^{im_{\pm} \varphi_1} e^{in_{\pm} \varphi_2} f_{\pm}(x_1, x_2) \tag{5.42}$$

should reduce these problems to second order decoupled partial differential equations for $f_k(x_1, x_2)$ and $f_{\pm}(x_1, x_2)$. We are interested in solving for the spectrum of eigenfrequencies ω_k and ω_{\pm} in terms of the two pairs of integers m_k and n_k , and m_{\pm} and n_{\pm} respectively.

6. Some instructive limits

In this section, we make a specific choice of the generic radial worldvolume coordinates x_1 and x_2 of Section 5. Our parameterization describes the full radial worldvolume of a submaximal giant graviton of size α_0 . Although it should, theoretically, be possible to write down the equations of motion (5.38)-(5.40) explicitly, it appears that these are too complex to obtain in full generality, even assisted by a numerical package such as Maple. We therefore confine our attention to the limiting case of the small giant graviton: the equations of motion are found to leading order and next-to-leading order in α_0 . Although we anticipate no dependence on the size α_0 at leading order, we hope to observe an α_0 -dependence in the spectrum at next-to-leading order, indicating that we are starting to probe the non-trivial geometry of the giant's worldvolume. The spectrum of the maximal giant graviton - being simply that of two dibaryons - is already known [26].

6.1 Radial worldvolume coordinates

The radial worldvolume of a submaximal giant graviton of size α_0 shall now be described using two sets of nested polar coordinates¹⁰ $(r_1(\alpha_0, \theta), \theta)$ and $(r_2(\alpha_0, \theta, \phi), \phi)$:

The giant graviton constraint equation (4.13) describes a surface in the radial space (y, z_1, z_2) . Let us first turn off one of the z_i coordinates, say z_2 , and parameterize the intersection of this surface with the yz_1 -plane. Setting $z_1 \equiv z$ and $z_2 = 0$ yields

$$(1 - y^2)(1 - z) = 1 - \alpha_0^2, \quad (6.1)$$

which is described by the polar ansatz $y \equiv r_1 \cos \theta$ and $\sqrt{z} \equiv r_1 \sin \theta$, if the polar radius $r_1(\alpha_0, \theta)$ satisfies

$$\sin^2(2\theta) r_1^4 - 4r_1^2 + 4\alpha_0^2 = 0. \quad (6.2)$$

To obtain the full surface, we need to extend this curve into the 3-dimensional radial space by requiring that the z_i coordinates now satisfy

$$(1 - z_1)(1 - z_2) = 1 - z = 1 - r_1^2 \sin^2 \theta. \quad (6.3)$$

Another polar ansatz $\sqrt{z_1} \equiv r_2 \cos \phi$ and $\sqrt{z_2} \equiv r_2 \sin \phi$ then yields the complete parameterization, if $r_2(\alpha_0, \theta, \phi)$ obeys

$$\sin^2(2\phi) r_2^4 - 4r_2^2 + 4r_1^2 \sin^2 \theta = 0. \quad (6.4)$$

Promoting α to a radial coordinate and defining

$$y = r_1(\alpha, \theta) \cos \theta \quad (6.5)$$

$$z_1 = r_2^2(\alpha, \theta, \phi) \cos^2 \phi \quad (6.6)$$

$$z_2 = r_2^2(\alpha, \theta, \phi) \sin^2 \phi, \quad (6.7)$$

with the polar radii r_1 and r_2 the positive roots of¹¹

$$r_1^2(\alpha, \theta) = \frac{2}{\sin^2(2\theta)} \left\{ 1 - \sqrt{1 - \alpha^2 \sin^2(2\theta)} \right\} \quad (6.8)$$

$$r_2^2(\alpha, \theta, \phi) = \frac{2}{\sin^2(2\phi)} \left\{ 1 - \sqrt{1 - r_1^2(\alpha, \theta) \sin^2 \theta \sin^2(2\phi)} \right\}, \quad (6.9)$$

we observe that $\alpha = \alpha_0$ describes the radial worldvolume of the submaximal giant graviton. Here the radial worldvolume coordinates $x_1 \equiv \theta \in [0, \pi]$ and $x_2 \equiv \phi \in [0, \frac{\pi}{2}]$ have fixed ranges (which is required by our general fluctuation analysis in Section 5).

¹⁰Note that this parameterization breaks the y^2 - z_i symmetry of the giant graviton constraint. This is perfectly reasonable, however, given the different coordinate ranges of y and z_i .

¹¹We have chosen the solution to each of the quadratic constraint equations (6.2) and (6.4) which avoids the singularities at $\theta = 0$ and $\theta = \pi$, and $\phi = 0$ respectively.

6.2 Small giant graviton

Leading order in α_0^2

Let us now focus on the small giant graviton, for which $0 < \alpha_0 \ll 1$. We can expand the square roots in r_1 and r_2 to leading order in α to obtain $r_1(\theta) \approx \alpha$ and $r_2(\theta, \phi) \approx \alpha \sin \theta$. Our radial coordinates then become

$$y \approx \alpha \cos \theta \quad (6.10)$$

$$z_1 \approx \alpha^2 \sin^2 \theta \cos^2 \phi \quad (6.11)$$

$$z_2 \approx \alpha^2 \sin^2 \theta \sin^2 \phi \quad (6.12)$$

in the vicinity of the $\alpha = \alpha_0$ surface. This approximate radial projection of the giant graviton is simply a 2-sphere in $(y, \sqrt{z_1}, \sqrt{z_2})$ -space.

The equations of motion were obtained from (5.38)-(5.40) to leading order in α_0 . Rescaling $\delta\tilde{\alpha} \equiv \alpha_0 \delta\alpha$, our results can be summarized as follows:

$$\left[M^{ab} \partial_a \partial_b + \hat{k}^a \partial_a + 1 \right] \delta v_k = 0 \quad (6.13)$$

$$\left[M^{ab} \partial_a \partial_b + k^a \partial_a \right] \delta\tilde{\alpha} + \left[\ell^a \partial_a \right] \delta\chi = 0 \quad (6.14)$$

$$\left[M^{ab} \partial_a \partial_b + \tilde{k}^a \partial_a \right] \delta\chi - \left[\tilde{\ell}^a \partial_a \right] \delta\tilde{\alpha} = 0, \quad (6.15)$$

where the inverse metric on the worldvolume of the giant graviton, rescaled by a factor of $(h^{tt})^{-1}$ for convenience, is approximated to leading order as follows:

$$M^{ab} \approx M_{(1)}^{ab} = \begin{pmatrix} 1 & 0 & 0 & -\frac{1}{2} & -\frac{1}{2} \\ 0 & -\frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & F_1 & 0 & 0 \\ -\frac{1}{2} & 0 & 0 & F_1 \sec^2 \phi + \frac{1}{4} & \frac{1}{4} \\ -\frac{1}{2} & 0 & 0 & \frac{1}{4} & F_1 \csc^2 \phi + \frac{1}{4} \end{pmatrix}, \quad (6.16)$$

while

$$\hat{k}^a \approx \hat{k}_{(1)}^a \equiv (0 \ F_2 \ F_4 \ 0 \ 0) \quad (6.17)$$

$$k^a \approx k_{(1)}^a \quad \text{and} \quad \tilde{k}^a \approx \tilde{k}_{(1)}^a, \quad \text{with} \quad k_{(1)}^a = \tilde{k}_{(1)}^a \equiv (0 \ F_3 \ F_4 \ 0 \ 0) \quad (6.18)$$

$$\ell^a \approx \ell_{(1)}^a \quad \text{and} \quad \tilde{\ell}^a \approx \tilde{\ell}_{(1)}^a, \quad \text{with} \quad \ell_{(1)}^a = \tilde{\ell}_{(1)}^a \equiv F_5 (-2 \ 0 \ 0 \ 1 \ 1), \quad (6.19)$$

in terms of the following functions of the radial worldvolume coordinates θ and ϕ :

$$F_1 = -\frac{(2 - \sin^2 \theta)}{4 \sin^2 \theta} \quad (6.20)$$

$$F_2 = -\frac{3}{2} \cot \theta \quad (6.21)$$

$$F_3 = -\frac{1}{2} \left[\frac{4}{(2 - \sin^2 \theta)} + 1 \right] \cot \theta \quad (6.22)$$

$$F_4 = F_1 (\cot \phi - \tan \phi) \quad (6.23)$$

$$F_5 = \frac{1}{(2 - \sin^2 \theta)}. \quad (6.24)$$

We are now able to decouple the leading order equations of motion (6.14)-(6.15) for the \mathbb{CP}^3 scalar fluctuations by defining $\delta\beta_{\pm} \equiv \tilde{\delta}\alpha \pm i\delta\chi$ to obtain

$$[M^{ab} \partial_a \partial_b + k^a \partial_a \mp i \ell^a \partial_a] \delta\beta_{\pm} \approx 0. \quad (6.25)$$

Let us now make the ansätze

$$\delta v_k(t, \theta, \phi, \varphi_1, \varphi_2) = e^{i\omega_k t} e^{im_k \varphi_1} e^{in_k \varphi_2} f_k(\theta, \phi) \quad (6.26)$$

$$\delta\beta_{\pm}(t, \theta, \phi, \varphi_1, \varphi_2) = e^{i\omega_{\pm} t} e^{im_{\pm} \varphi_1} e^{in_{\pm} \varphi_2} f_{\pm}(\theta, \phi), \quad (6.27)$$

with m_k and n_k , and m_{\pm} and n_{\pm} integers. The leading order decoupled equations of motion (6.13) and (6.25) become

$$\left\{ \frac{1}{2} \partial_{\theta}^2 - F_1 \partial_{\phi}^2 - F_2 \partial_{\theta} - F_4 \partial_{\phi} + [\tilde{\omega}_k^2 + (F_1 \sec^2 \phi) m_k^2 + (F_1 \csc^2 \phi) n_k^2 - 1] \right\} f_k(\theta, \phi) = 0 \quad (6.28)$$

$$\left\{ \frac{1}{2} \partial_{\theta}^2 - F_1 \partial_{\phi}^2 - F_3 \partial_{\theta} - F_4 \partial_{\phi} + [\tilde{\omega}_{\pm}^2 \pm 2F_5 \tilde{\omega}_{\pm} + (F_1 \sec^2 \phi) m_{\pm}^2 + (F_1 \csc^2 \phi) n_{\pm}^2] \right\} f_{\pm}(\theta, \phi) = 0, \quad (6.29)$$

where we have shifted the eigenfrequencies as follows:

$$\tilde{\omega}_k = \omega_k - \frac{1}{2} (m_k + n_k) \quad \text{and} \quad \tilde{\omega}_{\pm} = \omega_{\pm} - \frac{1}{2} (m_{\pm} + n_{\pm}). \quad (6.30)$$

These second order partial differential equations admit separable ansätze

$$f_k(\theta, \phi) \equiv \Theta_k(\theta) \Phi_k(\phi) \quad \text{and} \quad f_{\pm}(\theta, \phi) \equiv \Theta_{\pm}(\theta) \Phi_{\pm}(\phi), \quad (6.31)$$

which reduce the problems to

$$\frac{d^2 \Theta_k}{d\theta^2} + 3 \cot \theta \frac{d\Theta_k}{d\theta} + \left[2(\tilde{\omega}_k^2 - 1) - \frac{\lambda_k(2 - \sin^2 \theta)}{2 \sin^2 \theta} \right] \Theta_k = 0 \quad (6.32)$$

$$\frac{d^2 \Phi_k}{d\phi^2} + (\cot \phi - \tan \phi) \frac{d\Phi_k}{d\phi} + [\lambda_k - m_k^2 \sec^2 \phi - n_k^2 \csc^2 \phi] \Phi_k = 0 \quad (6.33)$$

and

$$\frac{d^2 \Theta_{\pm}}{d\theta^2} + \left[\frac{4}{(2 - \sin^2 \theta)} + 1 \right] \cot \theta \frac{d\Theta_{\pm}}{d\theta} + \left[2\tilde{\omega}_{\pm}^2 \pm \frac{4\tilde{\omega}_{\pm}}{(2 - \sin^2 \theta)} - \frac{\lambda_{\pm}(2 - \sin^2 \theta)}{2 \sin^2 \theta} \right] \Theta_{\pm} = 0 \quad (6.34)$$

$$\frac{d^2 \Phi_{\pm}}{d\phi^2} + (\cot \phi - \tan \phi) \frac{d\Phi_{\pm}}{d\phi} + [\lambda_{\pm} - m_{\pm}^2 \sec^2 \phi - n_{\pm}^2 \csc^2 \phi] \Phi_{\pm} = 0, \quad (6.35)$$

with λ_k and λ_{\pm} constant. The solutions of these second order ordinary differential equations, on the intervals $\theta \in [0, \pi]$ and $\phi \in [0, \frac{\pi}{2}]$ respectively, can be obtained in terms of hypergeometric and Heun functions, as we shall now briefly describe. It is clear, however, even without the solutions, that the spectrum of energy eigenvalues ω_k and ω_{\pm} is independent of the size α_0 of the giant graviton to leading order.

The differential equations (6.33) and (6.35), which describe the ϕ dependence of the scalar fluctuations of the AdS and \mathbb{CP}^3 coordinates respectively, take the same generic form. Taking the ansatz $\Phi(z) = z^{\frac{1}{2}|m|} (1-z)^{\frac{1}{2}|n|} g(z)$, with $z \equiv \cos^2 \phi \in [0, 1]$, these can be written in the standard hypergeometric form¹²

$$z(1-z) \frac{d^2 g}{dz^2} + [(|m|+1) - (|m|+|n|+2)] \frac{dg}{dz} - \frac{1}{4} [(|m|+|n|+1)^2 - (\lambda+1)] g = 0. \quad (6.36)$$

Similar problems were studied in [25, 26, 37]. The solutions $g(z) = F(a, b, c; z)$ are hypergeometric functions, dependent on the usual constants

$$a, b \equiv \frac{1}{2} \left\{ |m| + |n| + 1 \pm \sqrt{\lambda + 1} \right\} \quad \text{and} \quad c \equiv |m| + 1, \quad (6.37)$$

which are regular on the interval $[0, 1]$ when a or b is a non-positive integer. Hence

$$|m| + |n| + 1 \pm \sqrt{\lambda + 1} = -2s_1, \quad \text{with} \quad s_1 \in \{0, 1, 2, \dots\}, \quad (6.38)$$

from which it follows that $\lambda = l(l+2)$, with $l \equiv 2s_1 + |m| + |n|$. Notice that these constants λ are just the usual eigenvalues of the Laplacian [38] on the complex projective space \mathbb{CP}^2 .

Let us first consider the second order differential equation (6.32), which describes the θ dependence of the scalar fluctuations of the AdS directions. If we now set $\Theta_k(x) \equiv x^{\frac{l_k}{2}} (1-x)^{\frac{l_k}{2}} h_k(x)$, with $x \equiv \sin^2 \frac{\theta}{2} \in [0, 1]$, this can be written in the standard hypergeometric form

$$x(1-x) \frac{d^2 h_k}{dx^2} + [(l_k+2) - 2(l_k+2)x] \frac{dh_k}{dx} - \left[\frac{1}{2} l_k^2 + 2l_k - 2(\tilde{\omega}_k^2 - 1) \right] h_k = 0, \quad (6.39)$$

where $\lambda_k = l_k(l_k+2)$, with $l_k \equiv 2s_{k,1} + |m_k| + |n_k|$, are the eigenvalues of the Φ_k differential equation (6.33). The solutions $h_k(x) = F(a_k, b_k, c_k; x)$ are associated with the usual hypergeometric parameters

$$a_k, b_k = \left(l_k + \frac{3}{2} \right) \pm \sqrt{\frac{1}{2} l_k^2 + l_k + \frac{9}{4} + 2(\tilde{\omega}_k^2 - 1)} \quad \text{and} \quad c_k = l_k + 2. \quad (6.40)$$

For regularity on $[0, 1]$, we require that either a_k or b_k be a non-positive integer:

$$\left(l_k + \frac{3}{2} \right) - \sqrt{\frac{1}{2} l_k^2 + l_k + \frac{9}{4} + 2(\tilde{\omega}_k^2 - 1)} = -s_{k,2}, \quad \text{with} \quad s_{k,2} \in \{0, 1, 2, \dots\}. \quad (6.41)$$

¹²Here we drop the k and \pm subscripts temporarily, since the same differential equation for $\Phi(\phi)$ applies in both cases.

We can hence determine an equation for the shifted frequencies squared of the AdS fluctuations about the small giant graviton to leading order in α_0 :

$$\begin{aligned}\tilde{\omega}_k^2 &= \left[\omega_k - \frac{1}{2}(m_k + n_k)\right]^2 \\ &= \frac{1}{2} \left[2s_{k,1} + s_{k,2} + |m_k| + |n_k| + \frac{3}{2}\right]^2 - \frac{1}{4} \left[2s_{k,1} + |m_k| + |n_k| + 1\right]^2 + \frac{1}{8}\end{aligned}\quad (6.42)$$

in terms of the non-negative integers $s_{k,1}$ and $s_{k,2}$. Notice that there are no complex energy eigenvalues, indicating stability. As expected, there are also no zero modes associated with the fluctuations in the AdS spacetime.

Let us focus momentarily on the s-modes, obtained by setting $s_{k,1} = s_{k,2} = 0$. We can express these lowest frequencies as follows:

$$\omega_k = \frac{1}{2}(m_k + n_k) \pm \left[\frac{1}{2}(|m_k| + |n_k|) + 1\right], \quad (6.43)$$

which can be divided into two cases, depending on the relative signs of m_k and n_k . More specifically, we find that

$$\begin{aligned}\omega_k &= \text{sign}(m_k) [|m_k| + |n_k| + 1] \quad \text{or} \quad \omega_k = -\text{sign}(m_k) 1, & \text{when } m_k n_k \geq 0 \\ \omega_k &= \text{sign}(m_k) [|m_k| + 1] \quad \text{or} \quad \omega_k = \text{sign}(n_k) [|n_k| + 1], & \text{when } m_k n_k < 0.\end{aligned}\quad (6.44)$$

We shall now consider the second order differential equation (6.34), which describes the θ dependence of the scalar fluctuations of the transverse \mathbb{CP}^3 coordinates. Setting $\Theta_{\pm}(\tilde{x}) \equiv x^{\frac{l_{\pm}}{2}}(1-x)^{\frac{l_{\pm}}{2}}h_{\pm}(\tilde{x})$, where $\tilde{x} = 4x(1-x)$ and $x \equiv \sin^2 \frac{\theta}{2}$ as before¹³, we obtain a Heun differential equation

$$\begin{aligned}\frac{d^2 h_{\pm}}{d\tilde{x}^2} + \left[\frac{(l_{\pm} + 2)}{\tilde{x}} + \frac{\frac{1}{2}}{(\tilde{x} - 1)} + \frac{(-1)}{(\tilde{x} - 2)} \right] \frac{dh_{\pm}}{d\tilde{x}} \\ + \frac{\left[\frac{1}{8}l_{\pm}^2 - \frac{1}{2}\tilde{\omega}_{\pm}^2 \right] \tilde{x} - \left[\frac{1}{4}(l_{\pm} + 1)^2 - (\tilde{\omega}_{\pm} + \frac{1}{2})^2 \right]}{\tilde{x}(\tilde{x} - 1)(\tilde{x} - 2)} h_{\pm} = 0.\end{aligned}\quad (6.45)$$

Again $\lambda_{\pm} = l_{\pm}(l_{\pm} + 2)$, with $l_{\pm} \equiv 2s_{\pm,1} + |m_{\pm}| + |n_{\pm}|$, are the eigenvalues of the Φ_{\pm} differential equation (6.35). The Heun solutions $h_{\pm}(\tilde{x}) = F(2, q_{\pm}; a_{\pm}, b_{\pm}, c_{\pm}, d_{\pm}; \tilde{x})$ depend on the parameters

$$a_{\pm}, b_{\pm} = \frac{1}{2} \left\{ l_{\pm} + \frac{1}{2} \pm \sqrt{\frac{1}{2}l_{\pm}^2 + l_{\pm} + \frac{1}{4} + 2\tilde{\omega}_{\pm}^2} \right\}, \quad c_{\pm} = l_{\pm} + 2, \quad d_{\pm} = \frac{1}{2}, \quad e_{\pm} = -1 \quad (6.46)$$

and the accessory parameter

$$q_{\pm} = \frac{1}{4}(l_{\pm} + 1)^2 - \left(\tilde{\omega}_{\pm} \pm \frac{1}{2}\right)^2. \quad (6.47)$$

¹³Note that θ runs over the interval $[0, \pi]$, so that $\tilde{x} = \sin^2 \theta$ double covers the interval $[0, 1]$, while $x \equiv \sin^2 \frac{\theta}{2}$ covers it only once.

There are several different regular classes of Heun functions [39]. All possible regular solutions are obtained, in this case, by requiring that either a_{\pm} or b_{\pm} be a non-positive integer or half-integer:

$$(l_{\pm} + \frac{1}{2}) - \sqrt{\frac{1}{2}l_{\pm}^2 + l_{\pm} + \frac{1}{4} + 2\tilde{\omega}_k^2} = -s_{\pm,2}, \quad \text{with } s_{\pm,2} \in \{0, 1, 2, \dots\}. \quad (6.48)$$

It is hence possible to find an equation for the shifted frequencies squared of the \mathbb{CP}^3 fluctuations about the small giant graviton to leading order in α_0 :

$$\begin{aligned} \tilde{\omega}_{\pm}^2 &= \left[\omega_{\pm} - \frac{1}{2}(m_{\pm} + n_{\pm})\right]^2 \\ &= \frac{1}{2} \left[2s_{\pm,1} + s_{\pm,2} + |m_{\pm}| + |n_{\pm}| + \frac{1}{2}\right]^2 - \frac{1}{4} \left[2s_{\pm,1} + |m_{\pm}| + |n_{\pm}| + 1\right]^2 + \frac{1}{8} \end{aligned} \quad (6.49)$$

in terms of the non-negative integers $s_{k,1}$ and $s_{k,2}$. Notice that, again, there are no complex energy eigenvalues, indicating stability.

The s-modes are associated with the lowest frequencies, obtained by setting $s_{\pm,1} = s_{\pm,2} = 0$, which are given by

$$\omega_{\pm} = \frac{1}{2}(m_{\pm} + n_{\pm}) \pm \frac{1}{2}(|m_{\pm}| + |n_{\pm}|). \quad (6.50)$$

If the integers m_{\pm} and n_{\pm} have the same sign, this yields simply $\omega_{\pm} = (m_{\pm} + n_{\pm})$ or $\omega_{\pm} = 0$, whereas, if m_{\pm} and n_{\pm} have different signs, we obtain $\omega_{\pm} = m_{\pm}$ or $\omega_{\pm} = n_{\pm}$. Notice that there are zero modes associated with these \mathbb{CP}^3 fluctuations. This is to be expected, since changing the size α_0 of the giant does not cost any extra energy. We anticipate that these lowest frequencies should match the conformal dimensions of BPS excitations of the dual ABJM subdeterminant operator.

Next-to-leading order in α_0

The equations of motion to next-to-leading order in α_0 can again be written in the form (6.13)-(6.15), where we now include an additional higher order term in the rescaled inverse worldvolume metric $M^{ab} \approx M_{(1)}^{ab} + \alpha_0 M_{(2)}^{ab}$, with

$$M_{(2)}^{ab} \equiv \cos \theta \begin{pmatrix} 0 & 0 & 0 & \frac{1}{2} & -\frac{1}{2} \\ 0 & \frac{1}{2} \cos(2\phi) & -\cot \theta \sin(2\phi) & 0 & 0 \\ 0 & -\cot \theta \sin(2\phi) & -\frac{1}{2} \cot^2 \theta \cos(2\phi) & 0 & 0 \\ \frac{1}{2} & 0 & 0 & \frac{1}{2} \cot^2 \theta \sec^2 \phi & 0 \\ -\frac{1}{2} & 0 & 0 & 0 & \frac{1}{2} \cot^2 \theta \csc^2 \phi \end{pmatrix}. \quad (6.51)$$

The other next-to-leading order coefficients are

$$\hat{k}^a \approx \hat{k}_{(1)}^a + \alpha_0 \hat{k}_{(2)}^a, \quad \text{with } \hat{k}_{(2)}^a \equiv (0 \ S_2 \ \hat{S}_4 \ 0 \ 0) \quad (6.52)$$

$$k^a \approx k_{(1)}^a + \alpha_0 k_{(2)}^a, \quad \text{with } k_{(2)}^a \equiv (0 \ S_3 \ S_4 \ 0 \ 0) \quad (6.53)$$

$$\tilde{k}^a \approx \tilde{k}_{(1)}^a + \alpha_0 \tilde{k}_{(2)}^a, \quad \text{with } \tilde{k}_{(2)}^a = k_{(2)}^a \quad (6.54)$$

$$\ell^a \approx \ell_{(1)}^a + \alpha_0 \ell_{(2)}^a, \quad \text{with } \ell_{(2)}^a \equiv S_5 (-2 \ 0 \ 0 \ 1 \ 1) - S_6 (0 \ 0 \ 0 \ 1 \ -1) \quad (6.55)$$

$$\tilde{\ell}^a \approx \tilde{\ell}_{(1)}^a + \alpha_0 \tilde{\ell}_{(2)}^a, \quad \text{with } \tilde{\ell}_{(2)}^a = \ell_{(2)}^a, \quad (6.56)$$

where

$$S_2(\theta, \phi) \equiv -\frac{1}{2} \csc \theta \cos(2\phi) \quad (6.57)$$

$$S_3(\theta, \phi) \equiv -\frac{\cos^2 \theta (4 + \sin^4 \theta)}{2 \sin \theta (2 - \sin^2 \theta)^2} \cos(2\phi) \quad (6.58)$$

$$\hat{S}_4(\theta, \phi) \equiv -\frac{\cos \theta}{\sin^2 \theta} [\cos^2 \theta \csc(2\phi) - \sin(2\phi)] \quad (6.59)$$

$$S_4(\theta, \phi) \equiv -\cot^2 \theta \cos \theta \csc(2\phi) + \frac{\cos \theta (3 + \cos^4 \theta)}{2 \sin^2 \theta (2 - \sin^2 \theta)} \sin(2\phi) \quad (6.60)$$

$$S_5(\theta, \phi) \equiv \frac{\sin^2 \theta \cos \theta}{(2 - \sin^2 \theta)^2} \cos(2\phi) \quad (6.61)$$

$$S_6(\theta) \equiv -\frac{\cos \theta (4 - \sin^2 \theta)}{2(2 - \sin^2 \theta)}. \quad (6.62)$$

These are simply the next-to-leading order functions to be associated with the leading order functions F_2 , F_3 and F_4 (which appears in both \hat{k}^a and k^a).

Notice that, since $k^a \approx \tilde{k}^a$ and $\ell^a \approx \tilde{\ell}^a$ to next-to-leading order in α_0 , the equations of motion for the \mathbb{CP}^3 fluctuations $\delta\tilde{\alpha}$ and $\delta\chi$ can still be decoupled by setting $\delta\beta_{\pm} \equiv \tilde{\delta}\alpha \pm i\delta\chi$. These equations of motion now become (6.25), as before, except in that M^{ab} , k^a and ℓ^a now include next-to-leading order terms.

Again taking ansätze of the form (6.26)-(6.27), describing the oscillatory behaviour of the temporal and angular worldvolume coordinates, the next-to-leading order equations of motion can be written as

$$\begin{aligned} & \left\{ \left[\frac{1}{2} - \frac{1}{2} \alpha_0 \cos \theta \cos(2\phi) \right] \partial_{\theta}^2 - \left[F_1 - \frac{1}{2} \alpha_0 \cos \theta \cot^2 \theta \cos(2\phi) \right] \partial_{\phi}^2 \right. \\ & + \left[2\alpha_0 \cos \theta \cot \theta \sin(2\phi) \right] \partial_{\theta} \partial_{\phi} - \left[F_2 + \alpha_0 S_2 \right] \partial_{\theta} - \left[F_4 + \alpha_0 \hat{S}_4 \right] \partial_{\phi} \\ & + \left[\tilde{\omega}_k^2 + \alpha_0 \cos \theta \tilde{\omega}_k (m_k - n_k) + \left(F_1 \sec^2 \phi + \frac{1}{2} \alpha_0 \cos \theta (\cot^2 \theta \sec^2 \phi + 1) \right) m_k^2 \right. \\ & \left. \left. + \left(F_1 \csc^2 \phi + \frac{1}{2} \alpha_0 \cos \theta (\cot^2 \theta \csc^2 \phi - 1) \right) n_k^2 - 1 \right] \right\} f_k(\theta, \phi) = 0 \quad (6.63) \end{aligned}$$

$$\begin{aligned} & \left\{ \left[\frac{1}{2} - \frac{1}{2} \alpha_0 \cos \theta \cos(2\phi) \right] \partial_{\theta}^2 - \left[F_1 - \frac{1}{2} \alpha_0 \cos \theta \cot^2 \theta \cos(2\phi) \right] \partial_{\phi}^2 \right. \\ & + \left[2\alpha_0 \cos \theta \cot \theta \sin(2\phi) \right] \partial_{\theta} \partial_{\phi} - \left[F_3 + \alpha_0 S_3 \right] \partial_{\theta} - \left[F_4 + \alpha_0 S_4 \right] \partial_{\phi} \\ & + \left[\tilde{\omega}_{\pm}^2 + \alpha_0 \cos \theta \tilde{\omega}_{\pm} (m_{\pm} - n_{\pm}) \pm 2(F_5 + \alpha_0 S_5) \tilde{\omega}_{\pm} \pm \alpha_0 S_6 (m_{\pm} - n_{\pm}) \right. \\ & \left. + \left(F_1 \sec^2 \phi + \frac{1}{2} \alpha_0 \cos \theta (\cot^2 \theta \sec^2 \phi + 1) \right) m_{\pm}^2 \right. \\ & \left. \left. + \left(F_1 \csc^2 \phi + \frac{1}{2} \alpha_0 \cos \theta (\cot^2 \theta \csc^2 \phi - 1) \right) n_{\pm}^2 \right] \right\} f_{\pm}(\theta, \phi) = 0, \quad (6.64) \end{aligned}$$

in terms of the shifted eigenfrequencies (6.30). These second order partial differential equations no longer admit separable ansätze. Note that m_k and n_k , as well as m_{\pm} and n_{\pm} , must be independent of the size α_0 - these are integers and hence cannot be

continuously varied as we change α_0 . However, we expect the frequencies $\omega_k(\alpha_0)$ and $\omega_{\pm}(\alpha_0)$ associated with each pair of integers to pick up an α_0 dependence, together with the eigenfunctions $f_k(\alpha_0, \theta, \phi)$ and $f_{\pm}(\alpha_0, \theta, \phi)$, since there is now an explicit dependence on α_0 in the next-to-leading order equations of motion.

Next-to-next-to-leading order in α_0

To obtain the leading and next-to-leading order equations of motion, it was sufficient to make use of the spherical parameterization (6.10) of the radial worldvolume. The next-to-leading order α_0 terms came from including additional α_0 terms in the metric and not from changing our parameterization of the radial surface. At higher orders, however, we need to include additional $O(\alpha^3)$ terms in the functions r_1 and r_2 , which describe the deviation of the radial worldvolume away from the spherical:

$$r_1(\theta) \approx \alpha \left\{ 1 + \frac{1}{2} \alpha^2 \sin^2 \theta \cos^2 \theta \right\} \quad (6.65)$$

$$r_2(\theta, \phi) \approx \alpha \sin \theta \left\{ 1 + \frac{1}{2} \alpha^2 \sin^4 \theta (\cos^2 \theta + \sin^2 \theta \cos^2 \phi \sin^2 \phi) \right\}. \quad (6.66)$$

We should hence make use of the radial coordinates

$$y \approx \alpha \left\{ 1 + \frac{1}{2} \alpha^2 \sin^2 \theta \cos^2 \theta \right\} \cos \theta \quad (6.67)$$

$$z_1 \approx \alpha^2 \sin^2 \theta \left\{ 1 + \alpha^2 \sin^4 \theta (\cos^2 \theta + \sin^2 \theta \cos^2 \phi \sin^2 \phi) \right\} \cos^2 \phi \quad (6.68)$$

$$z_2 \approx \alpha^2 \sin^2 \theta \left\{ 1 + \alpha^2 \sin^4 \theta (\cos^2 \theta + \sin^2 \theta \cos^2 \phi \sin^2 \phi) \right\} \sin^2 \phi. \quad (6.69)$$

We have not written down the next-to-next-to-leading order equations of motion for the scalar fluctuations δv_k , $\delta \tilde{\alpha}$ and $\delta \chi$, since an α_0 -dependence (at least at the level of the decoupled equations of motion) has already been observed at next-to-leading order. However, in this case, we anticipate that the equations of motion for the \mathbb{CP}^3 scalar fluctuations $\delta \tilde{\alpha}$ and $\delta \chi$ will no longer trivially decouple.

7. Discussion and an outlook to the future

Showing that all of spacetime and its various properties, size, shape, geometry, topology, locality and causality, are phenomena that are not fundamental but emergent through a vast number of quantum interactions is as ambitious a goal as any in the history of physics. While it is not usually understood as one of the goals of string theory *per se*¹⁴, string theory does bring a formidable set of tools to bear on the problem via the AdS/CFT correspondence.

¹⁴Indeed, over the past decade, it has been a fertile pursuit for a number of research programs in quantum gravity [40].

This article aims to draw attention to the question of how the *nontrivial* geometry of a D4-brane giant graviton in type IIA string theory on $AdS_4 \times \mathbb{CP}^3$ is encoded in the dual ABJM super Chern-Simons theory. To this end, we have focused on the gravity side of the correspondence and, in particular, on the construction of the giant graviton solution. In this sense, this work can be seen as a natural extension of the research program initiated in [25] and continued in [26]. In the former we showed how to implement Mikhailov’s holomorphic curve prescription [24] to construct giant gravitons on $AdS_5 \times T^{1,1}$. Guided by that construction and the similarities between the ABJM and Klebanov-Witten models, we formulate an ansatz for the D4-brane giant graviton extended and moving in \mathbb{CP}^3 and show that it is energetically degenerate with the point graviton. We show also that as the giant grows to maximal size it pinches off into two D4-branes, each wrapping a $\mathbb{CP}^2 \subset \mathbb{CP}^3$ with opposite orientation (preserving the D4-brane charge neutrality of the configuration). This is in excellent agreement with the expectation from the gauge theory in which the operators dual to the giant graviton are (i) determinant-like and (ii) built from composite fields of the form AB , which factorize at maximal size into dibaryon operators as $\det(AB) = \det(A) \det(B)$.

The spectrum of small fluctuations about this solution, however, has proven to be a much more technically challenging problem. Encouraged by our success in computing the fluctuation spectrum of the giant graviton on $AdS_5 \times T^{1,1}$, we pursued an analogous line of computation here only to find the resulting system of fluctuation equations not analytically tractable in general. We were, however, able to make some progress in the case of a *small* giant graviton (parameterized by $0 < \alpha_0 \ll 1$). Here we were able to solve the decoupled fluctuation equations exactly in terms of hypergeometric and Heun functions. We found that, for both the scalar fluctuations of the AdS_4 and \mathbb{CP}^3 transverse coordinates, all eigenvalues are real indicating that the D4-brane giant is, at least to this order in the approximation, perturbatively stable. The zero-mode structure of the spectrum is also in keeping with our expectations: there are no zero modes in the AdS_4 part of the spectrum and a zero mode in the spectrum of \mathbb{CP}^3 fluctuations corresponding to the fact that it costs no extra energy to increase the size of the giant. More generally though, we were unable to find a global parameterization of the D-brane worldvolume for which the entire spectrum could be read off. Still, there are several interesting observations that can be made:

- i) Unlike the spherical dual D2-brane giant graviton [20, 22] for which mixing between longitudinal (worldvolume) and transverse (scalar) fluctuations gives rise to a massless Goldstone mode that hints towards a solution carrying both momentum and D0-brane charge, no such coupling between gauge field and scalar fluctuations occurs for the D4-brane giant.
- ii) While our parameterization does not allow us to solve the fluctuation equations

in full generality, by expanding in α_0 , we see hints of a dependence on the size of the giant in the spectrum at subleading order in the perturbation series. Should this prove a robust feature of the spectrum, as we expect from our study of the $T^{1,1}$ giant, it will furnish one of the most novel tests of the Giant Graviton/Schur Polynomial correspondence to date. This in itself is, in our opinion, sufficient reason to continue the study of this solution.

Evidently then, our study of the D4-brane giant graviton presents just as many (if not more) questions than answers. These include:

- i) *How much supersymmetry does the D4-brane giant preserve?* To answer this, a detailed analysis of the Killing spinor equations along the lines of [20, 41], needs to be undertaken.
- ii) *Are these configurations perturbatively stable?* Even though, as we have demonstrated, the D4-brane giant is energetically degenerate with the point graviton, it remains to be shown that the fluctuation spectrum is entirely real *i.e. there are no tachyonic modes present*.
- iii) *What are the precise operators dual to the giant and its excitations?* Based on the lessons learnt from $\mathcal{N} = 4$ SYM theory, it seems clear that the operators in the ABJM model dual to giant gravitons are Schur polynomials constructed from composite scalars in the supermultiplet (see Section 2 and the related work in [33]). What is not clear is whether the associated *restricted* Schur polynomials, which correspond to excitations of the giant, form a complete, orthonormal basis that diagonalizes the 2-point function.

We hope that, if nothing else, this work stimulates more research on this fascinating class of solutions of the type IIA superstring on $AdS_4 \times \mathbb{CP}^3$.

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A. Type IIA string theory on $AdS_4 \times \mathbb{CP}^3$

Herein we present a brief description of the $AdS_4 \times \mathbb{CP}^3$ background, which is a solution of the type IIA 10D SUGRA equations of motion. Making use of a Hopf fibration of S^7 over \mathbb{CP}^3 , this background can also be obtained by a Kaluza-Klein dimensional reduction of the $AdS_4 \times S^7$ solution of 11D SUGRA [42].

The $AdS_4 \times \mathbb{CP}^3$ metric is given by

$$ds^2 = R^2 \{ ds_{AdS_4}^2 + 4 ds_{\mathbb{CP}^3}^2 \}, \quad (\text{A.1})$$

with R the radius of the anti-de Sitter and complex projective spaces. The anti-de Sitter metric, in the usual global coordinates, takes the form

$$ds_{AdS_4}^2 = - (1 + r^2) dt^2 + \frac{dr^2}{(1 + r^2)} + r^2 \left(d\tilde{\theta}^2 + \sin^2 \tilde{\theta} d\tilde{\varphi}^2 \right). \quad (\text{A.2})$$

Let us make use of a slight variation of the parameterization of [20] to describe the four homogenous coordinates z^a of the complex projective space as follows:

$$\begin{aligned} z^1 &= \cos \zeta \sin \frac{\theta_1}{2} e^{i(y + \frac{1}{4}\psi - \frac{1}{2}\phi_1)} & z^2 &= \cos \zeta \cos \frac{\theta_1}{2} e^{i(y + \frac{1}{4}\psi + \frac{1}{2}\phi_1)} \\ z^3 &= \sin \zeta \sin \frac{\theta_2}{2} e^{i(y - \frac{1}{4}\psi + \frac{1}{2}\phi_2)} & z^4 &= \sin \zeta \cos \frac{\theta_2}{2} e^{i(y - \frac{1}{4}\psi - \frac{1}{2}\phi_2)}, \end{aligned} \quad (\text{A.3})$$

with radial coordinates $\zeta \in [0, \frac{\pi}{2}]$ and $\theta_i \in [0, \pi]$, and angular coordinates $y, \phi_i \in [0, 2\pi]$ and $\psi \in [0, 4\pi]$. These describe the magnitudes and phases of the homogenous coordinates respectively. Note that the three inhomogenous coordinates $\frac{z^1}{z^4}, \frac{z^2}{z^4}$ and $\frac{z^3}{z^4}$ of \mathbb{CP}^3 are independent of the total phase y . The Fubini-Study metric of the complex projective space can now be written as

$$\begin{aligned} ds_{\mathbb{CP}^3}^2 &= d\zeta^2 + \frac{1}{4} \cos^2 \zeta \sin^2 \zeta [d\psi + \cos \theta_1 d\phi_1 + \cos \theta_2 d\phi_2]^2 \\ &\quad + \frac{1}{4} \cos^2 \zeta (d\theta_1^2 + \sin^2 \theta_1 d\phi_1^2) + \frac{1}{4} \sin^2 \zeta (d\theta_2^2 + \sin^2 \theta_2 d\phi_2^2). \end{aligned} \quad (\text{A.4})$$

There is also a constant dilaton $e^{2\Phi} = \frac{4R^2}{k^2}$ and the following even dimensional field strengths:

$$\begin{aligned} F_2 &= 2kJ = -\frac{1}{2}k \{ \sin(2\zeta) d\zeta \wedge [d\psi + \cos \theta_1 d\phi_1 + \cos \theta_2 d\phi_2] \\ &\quad + \cos^2 \zeta \sin \theta_1 d\theta_1 \wedge d\phi_1 - \sin^2 \zeta \sin \theta_2 d\theta_2 \wedge d\phi_2 \} \end{aligned} \quad (\text{A.5})$$

$$F_4 = -\frac{3}{2}kR^2 \text{vol}(AdS_4) = -\frac{3}{2}kR^2 r^2 \sin \tilde{\theta} dt \wedge dr \wedge d\tilde{\theta} \wedge d\tilde{\varphi}, \quad (\text{A.6})$$

with Hodge duals $F_6 = *F_4$ and $F_8 = *F_2$. In particular, the 6-form field strength can be calculated to be

$$\begin{aligned} F_6 &= \frac{3}{2} (64) kR^4 \text{vol}(\mathbb{CP}^3) \\ &= 3kR^4 \cos^3 \zeta \sin^3 \zeta \sin \theta_1 \sin \theta_2 d\zeta \wedge d\theta_1 \wedge d\theta_2 \wedge d\psi \wedge d\phi_1 \wedge d\phi_2. \end{aligned} \quad (\text{A.7})$$

B. Energy and momentum integrals

In this appendix, we provide some of the details of our numerical determination of the energy integral (4.32) at fixed momentum P_χ , given by integral (4.30), as a function of α (shown in Figure 2 of Section 4).

B.1 Coordinate change

The Lagrangian, momentum and energy (4.28), (4.30) and (4.32) of the D4-brane configuration are given, as functions of the size α and angular velocity $\dot{\chi}$, in terms of the associated densities (4.29), (4.31) and (4.33) in the radial (y, z_1) worldvolume space. Let us now make the following coordinate change:

$$u \equiv (1+y)(1-z_1) \quad \text{and} \quad v \equiv (1-z_1). \quad (\text{B.1})$$

The Lagrangian, momentum and energy integrals then become

$$L = \int_{1-\alpha}^{1+\alpha} du \int_{V(u)}^1 dv \mathcal{L}(u, v) \quad (\text{B.2})$$

$$P_\chi = \int_{1-\alpha}^{1+\alpha} du \int_{V(u)}^1 dv \mathcal{P}_\chi(u, v) \quad (\text{B.3})$$

$$H = \int_{1-\alpha}^{1+\alpha} du \int_{V(u)}^1 dv \mathcal{H}(u, v), \quad (\text{B.4})$$

with

$$V(u) \equiv \frac{u^2}{2u - (1 - \alpha^2)} \quad (\text{B.5})$$

in terms of the new densities in the radial (u, v) worldvolume space:

$$\mathcal{L}(u, v) = \frac{1}{v^2} \tilde{\mathcal{L}}(u), \quad \mathcal{P}_\chi(u, v) = \frac{1}{v^2} \tilde{\mathcal{P}}_\chi(u) \quad \text{and} \quad \mathcal{H}(u, v) = \frac{1}{v^2} \tilde{\mathcal{H}}(u). \quad (\text{B.6})$$

Here we are able to pull out an overall $\frac{1}{v^2}$ dependence and define

$$\tilde{\mathcal{L}}(u) = \frac{N}{4} \left\{ \sqrt{2(1-\alpha^2)u - (1-\alpha^2) - u^2} \sqrt{2(1-\alpha^2)u\dot{\chi}^2 - (1-\alpha^2) - u^2} \right. \\ \left. + \dot{\chi} [u^2 + (1-\alpha^2) - 2(1-\alpha^2)u] \right\} \quad (\text{B.7})$$

$$\tilde{\mathcal{P}}_\chi(u) = \frac{N}{4} \left\{ \frac{2\dot{\chi}(1-\alpha^2)\sqrt{2(1-\alpha^2)u - (1-\alpha^2) - u^2}}{\sqrt{2(1-\alpha^2)u\dot{\chi}^2 - (1-\alpha^2) - u^2}} + \frac{1}{u} [u^2 + (1-\alpha^2) - 2(1-\alpha^2)u] \right\} \quad (\text{B.8})$$

$$\tilde{\mathcal{H}}(u) = \frac{N}{4} \frac{1}{u} [u^2 + (1-\alpha^2)] \frac{\sqrt{2(1-\alpha^2)u - (1-\alpha^2) - u^2}}{\sqrt{2(1-\alpha^2)u\dot{\chi}^2 - (1-\alpha^2) - u^2}}. \quad (\text{B.9})$$

Explicitly computing the integral over v as follows:

$$\int_{1-\alpha}^{1+\alpha} du \int_{V(u)}^1 \frac{dv}{v^2} = \frac{2u - [u^2 + (1 - \alpha^2)]}{u^2}, \quad (\text{B.10})$$

we can now write

$$L = \int_{1-\alpha}^{1+\alpha} du \bar{\mathcal{L}}_{\text{D4}}(u), \quad \text{with } \bar{\mathcal{L}}(u) = \frac{2u - [u^2 + (1 - \alpha^2)]}{u^2} \tilde{\mathcal{L}}(u) \quad (\text{B.11})$$

$$P_\chi = \int_{1-\alpha}^{1+\alpha} du \bar{\mathcal{P}}_\chi(u), \quad \text{with } \bar{\mathcal{P}}_\chi(u) = \frac{2u - [u^2 + (1 - \alpha^2)]}{u^2} \tilde{\mathcal{P}}_\chi(u) \quad (\text{B.12})$$

$$H = \int_{1-\alpha}^{1+\alpha} du \bar{\mathcal{H}}(u), \quad \text{with } \bar{\mathcal{H}}(u) = \frac{2u - [u^2 + (1 - \alpha^2)]}{u^2} \tilde{\mathcal{H}}(u). \quad (\text{B.13})$$

B.2 Momentum integral

The momentum integral (B.12) was calculated numerically using standard quadrature routines. Our result is shown in the form of a surface $P_\chi(\alpha, \dot{\chi})$ in Figure 5 below.

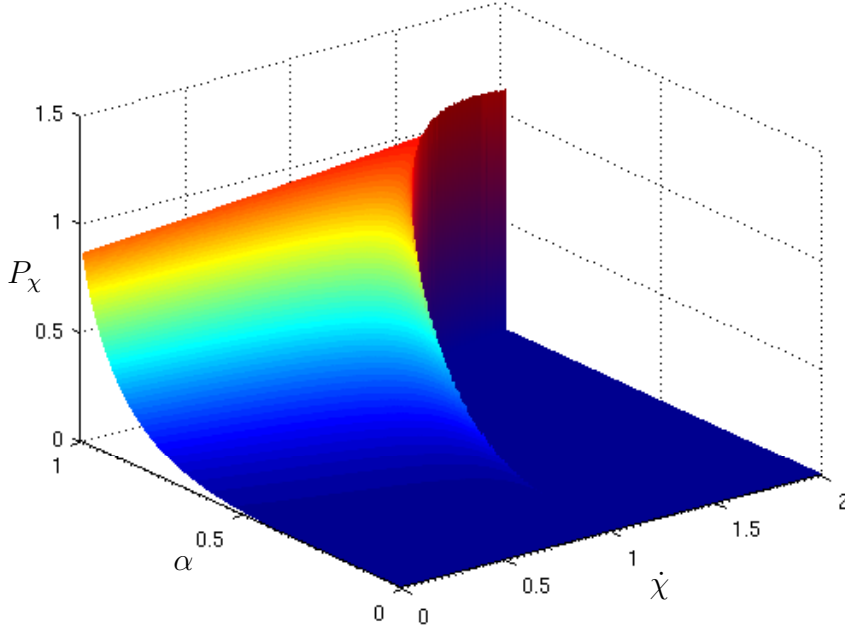


Figure 5: The momentum surface $P_\chi(\alpha, \dot{\chi})$ plotted in units of the flux N . The discontinuity curve is clearly evident.

The most striking feature is the presence of a singularity along the curve¹⁵

$$\dot{\chi}^4 = \frac{1}{1 - \alpha^2} \quad (\text{B.14})$$

on the $\alpha\dot{\chi}$ -plane. The existence of this singularity means that we should approach the energy integral with some caution.

B.3 Energy integral

We would now like to calculate the energy integral (B.13) at fixed momentum P_χ as a function of α . Making use of the $P_\chi(\alpha, \dot{\chi})$ surface, it is possible to plot contours of constant momentum on the $\alpha\dot{\chi}$ -plane (see Figure 6).

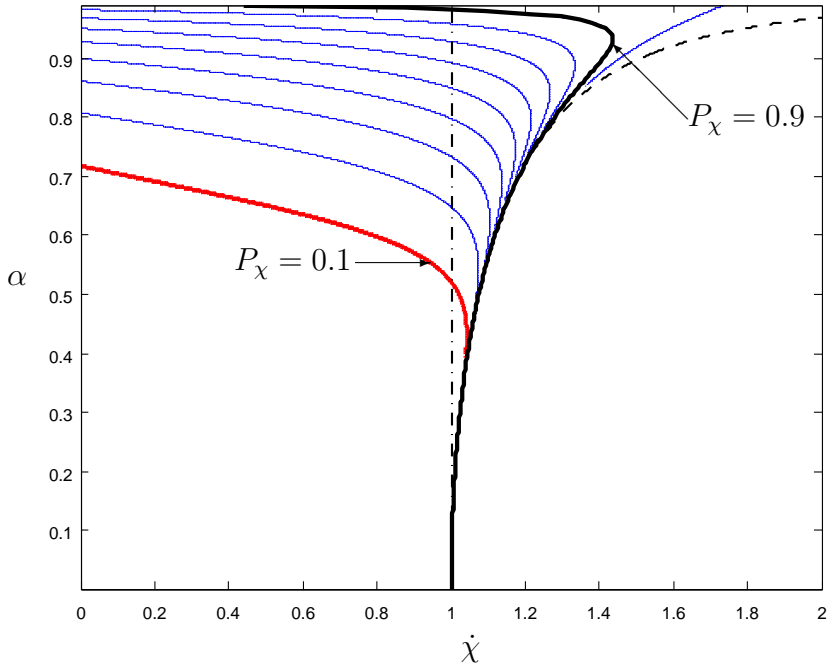


Figure 6: Lines of constant momentum P_χ . The dashed curve describes the discontinuity.

In principle, we can numerically integrate the energy (B.13) along any contour $\dot{\chi}(\alpha)$ at fixed momentum P_χ . These contours all approach the discontinuity, however, which places practical constraints upon how far along the contour we can perform the numerical integration. An alternative approach to the direct integration of (B.13) therefore needs to be found.

¹⁵Unlike the canonical sphere-giant case in $AdS_5 \times S^5$, in which the singularity occurs only at $\alpha = 0$, here the discontinuity traces out an entire curve. This happens at angular velocities $\dot{\chi}$ always bigger than one (and therefore never effects the giant graviton solution). Perhaps we can interpret this effect physically as a limiting velocity $(1 - \alpha^2)^{\frac{1}{2}} \dot{\chi}_{\text{discontinuity}} = (1 - \alpha^2)^{\frac{1}{4}} \leq 1$.

The Hamiltonian

$$H = \dot{\chi}P_\chi - L \tag{B.15}$$

has a singularity along the same curve (B.14) as the momentum P_χ . The Lagrangian L , however, is devoid of any such defect. Fixing P_χ and moving along this contour (in the direction of decreasing α), we can determine $\dot{\chi}(\alpha)$ up until a certain point, at which the contour becomes too close to the singularity to distinguish between the two and the numerics break down. At this point, however, we can simply use the curve (B.14) of the discontinuity itself to obtain a good approximation for $\dot{\chi}(\alpha)$. The full contour $\dot{\chi}(\alpha)$ can then be obtained using a cubic spline interpolation between the numerical contour and the discontinuity curve in the vicinity of this point (the position of which depends on the particular contour in question). We have considered $P_\chi = 0.2, 0.4, 0.6$ and 0.8 as examples, and Figure 7 shows the full contour $\dot{\chi}(\alpha)$, obtained using this interpolation technique, in each of these cases. Having obtained $\dot{\chi}(\alpha)$ along a fixed P_χ contour, there is no further hinderance to integrating the Lagrangian $L(\alpha, \dot{\chi}(\alpha))$ numerically using (B.11), since it is non-singular, and hence determining the energy (B.13).

C. d'Alembertian on the giant graviton's worldvolume

The metric on the worldvolume of the giant graviton in the worldvolume coordinates $\sigma^a = (t, x_1, x_2, \varphi_1, \varphi_2)$ can be written as

$$h_{ab} = \begin{pmatrix} -1 + g_{\chi\chi} & 0 & 0 & g_{\chi\varphi_1} & g_{\chi\varphi_2} \\ 0 & g_{x_1x_1} & g_{x_1x_2} & 0 & 0 \\ 0 & g_{x_1x_2} & g_{x_2x_2} & 0 & 0 \\ g_{\chi\varphi_1} & 0 & 0 & g_{\varphi_1\varphi_1} & g_{\varphi_1\varphi_2} \\ g_{\chi\varphi_2} & 0 & 0 & g_{\varphi_1\varphi_2} & g_{\varphi_2\varphi_2} \end{pmatrix}, \tag{C.1}$$

in terms of the components of the angular and radial metrics of the complex projective space (evaluated at $\alpha = \alpha_0$). The inverse metric h^{ab} can thus be expressed in terms of cofactors as follows:

$$h^{ab} = \begin{pmatrix} h^{tt} & 0 & 0 & h^{t\varphi_1} & h^{t\varphi_2} \\ 0 & h^{x_1x_1} & h^{x_1x_2} & 0 & 0 \\ 0 & h^{x_1x_2} & h^{x_2x_2} & 0 & 0 \\ h^{t\varphi_1} & 0 & 0 & h^{\varphi_1\varphi_1} & h^{\varphi_1\varphi_2} \\ h^{t\varphi_2} & 0 & 0 & h^{\varphi_1\varphi_2} & h^{\varphi_2\varphi_2} \end{pmatrix}, \tag{C.2}$$

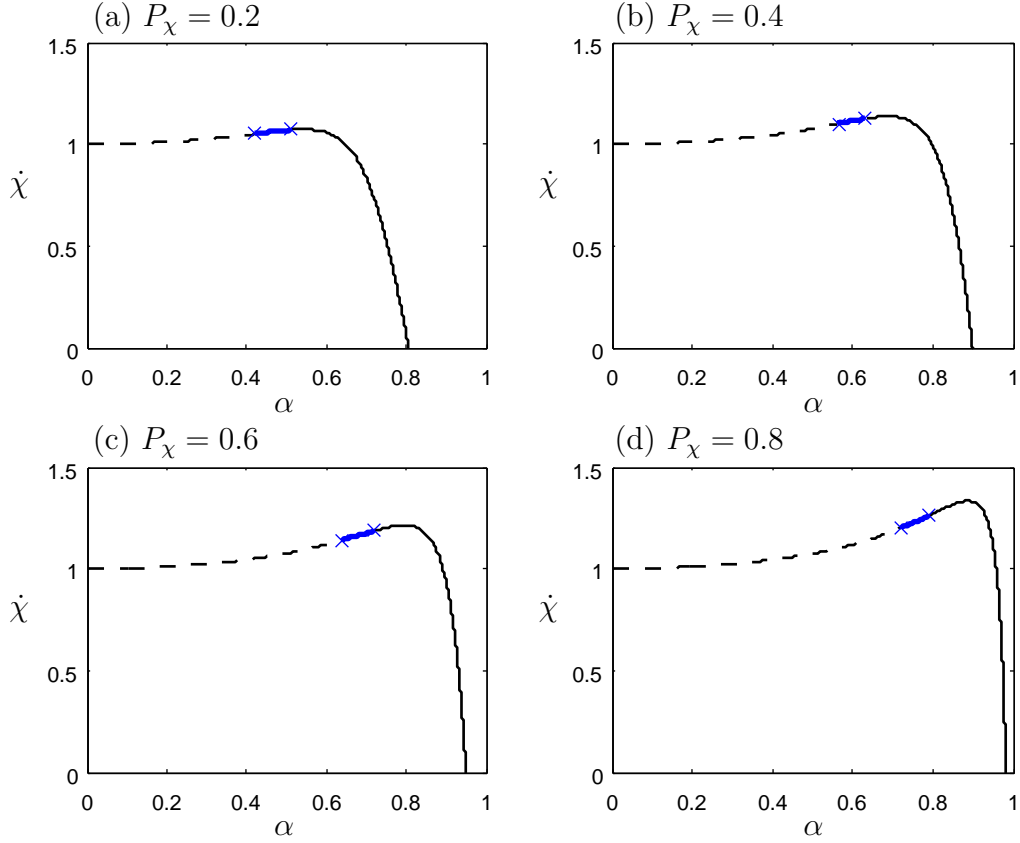


Figure 7: The relationship between $\dot{\chi}$ and α for fixed momentum. The curves show the results from the fixed momentum contour plot (rightmost section of the curve), together with the discontinuity curve (the leftmost dashed curve), given by $\dot{\chi}^4 = \frac{1}{1-\alpha^2}$. The section of curve between the two \times 's is obtained by cubic spline interpolation.

with temporal and angular inverse worldvolume metric components

$$\begin{aligned}
h^{tt} &= -\frac{(C_{\text{ang}})_{11}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} & h^{t\varphi_1} &= -\frac{(C_{\text{ang}})_{12}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \\
h^{t\varphi_2} &= -\frac{(C_{\text{ang}})_{13}}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} & h^{\varphi_1\varphi_1} &= -\frac{[(C_{\text{ang}})_{22} - g_{\varphi_2\varphi_2}]}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \\
h^{\varphi_2\varphi_2} &= -\frac{[(C_{\text{ang}})_{33} - g_{\varphi_1\varphi_1}]}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} & h^{\varphi_1\varphi_2} &= -\frac{[(C_{\text{ang}})_{23} + g_{\varphi_1\varphi_2}]}{[(C_{\text{ang}})_{11} - \det g_{\text{ang}}]} \tag{C.3}
\end{aligned}$$

and radial inverse worldvolume metric components

$$h^{x_1x_1} = \frac{g_{x_2x_2}}{(C_{\text{rad}})_{11}} \quad h^{x_2x_2} = \frac{g_{x_1x_1}}{(C_{\text{rad}})_{11}} \quad h^{x_1x_2} = -\frac{g_{x_1x_2}}{(C_{\text{rad}})_{11}}. \tag{C.4}$$

The invariant volume form on this worldvolume space is given by

$$\omega = \sqrt{-h} \, dt \wedge dx_1 \wedge dx_2 \wedge d\varphi_1 \wedge d\varphi_2, \tag{C.5}$$

where

$$\sqrt{-h} = \sqrt{(C_{\text{rad}})_{11} [(C_{\text{ang}})_{11} - \det g_{\text{ang}}]}. \quad (\text{C.6})$$

The gradient squared of an arbitrary function $f(\sigma^a)$ can be written in the compact notation

$$(\partial f)^2 \equiv h^{ab} (\partial_a f) (\partial_b f) \quad (\text{C.7})$$

and hence the d'Alembertian operator on the worldvolume of the giant graviton takes the form

$$\square \equiv \frac{1}{\sqrt{-h}} \partial_a \left(\sqrt{-h} h^{ab} \partial_b \right) = h^{ab} \partial_a \partial_b + \frac{1}{\sqrt{-h}} \partial_a \left(\sqrt{-h} h^{ab} \right) \partial_b. \quad (\text{C.8})$$

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