Low-complexity Energy-efficient Joint Resource Allocation for Two-hop MIMO-AF Systems

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Abstract—Energy efficiency (EE) is becoming an important system design criterion to ensure that the next generation of communication networks is sustainable. Equally, cooperative communication and resource allocation are well-known techniques for improving the performance of communication systems. In this paper, we propose a low-complexity energy-efficient joint resource allocation method for the two-hop multiple-input-multiple-output (MIMO) amplify-and-forward (AF) system. We derive explicit formulations of the near-optimal energy-per-bit consumption, subchannels’ power and rate for the unconstrained, total transmit power and sum-rate constrained EE optimization problems as well as detail how to solve these problems in a low-complexity manner. We then use our novel method for comparing the performances of two-hop MIMO-AF and MIMO systems in terms of EE. Our results indicate that the usage of a relay is only energy efficient when the quality of the direct link is very poor. We also show that the extra fixed power consumption induced by transmitting over two hops can seriously disadvantage MIMO-AF in terms of EE, but on the other hand, the usage of relay can be useful for downsizing the donor cell, which in turn provides EE gain.

Index Terms—Energy efficiency, resource allocation, MIMO, amplify-and-forward, realistic power model.

I. INTRODUCTION

Spectral efficiency (SE) remains the criterion of choice for assessing system performances and designing reliable and scalable communication systems. However, network operators require the next generation of communication systems to be low-energy consuming for both ensuring the economic and environmental sustainability of their activity. In this respect, energy efficiency (EE) is becoming increasingly important as a system performance criterion, and has recently attracted a surge of interest in the research community [1]–[3]. Although, EE has been extensively discussed in the past for power-limited as well as battery-driven systems [4]–[6], it remains a fairly new concept for power-unlimited communication systems, such as cellular networks [7], [8].

One of the possible approaches to make networks more energy efficient is the use of cooperative communication. Cooperative communication is a well-documented research area [9]–[12], which has proved to be an effective solution for increasing the spectral efficiency and/or the coverage of cellular networks [12] as well as reducing the cost of network deployment [13]. Among the existing relaying techniques, e.g. amplify and forward (AF), decode and forward as well as compress and forward, AF remains the most simple and practical approach for implementing cooperative multi-input multi-output (MIMO) communication. Consequently, it has attracted a plethora of contributions on SE-optimal precoding/resource allocation when considering either separate [14]–[17] or joint [18]–[20] allocation at the source node (SN) and relay node (RN). In the past, resource allocation has been extensively utilized for improving the SE or peak rate performance of communication systems [21], [22], but with little if any consideration about the energy consumption. Given the growing importance of the EE as a system design criterion, EE-based resource allocation is gaining momentum over SE-based resource allocation [23]–[27]. For instance, EE-optimal resource allocation schemes for the uplink and downlink of MIMO systems over a frequency selective channel have been recently proposed in [24], [25] and [26], [27], respectively. As far as relaying systems are concerned, EE-optimal resource allocation for a single antenna relay system in the low-power regime has been studied in [28]; in addition, energy-efficient power allocation for a single antenna AF OFDM system and one/two-way AF systems have been proposed in [29] and [30], respectively. More recently, energy-efficient power allocation has also been investigated for the multi-relay and relay assisted interference scenarios in [31] and [32], respectively. In the two-hop MIMO-AF scenario, the work in [33] first proposes an energy-efficient power allocation method for independently allocating resources at SN or RN when considering as in [14]–[16] that full channel state information (CSI), i.e. transmit and receive CSI, is available at the relay and transmit CSI is also available at the SN. It then uses a holistic iterative method for performing the joint optimization.

In this paper, we also propose an energy-efficient resource allocation method for the two-hop MIMO-AF system with the same CSI assumption as in [33]. Contrary to the latter, we directly solve the energy-efficient joint optimization of the SN and RN resources such as in [18], [20] but when considering the EE as an objective function instead of SE or minimum squared error. In addition, as opposed to [33], we consider the total power consumed in the MIMO-AF system based on realistic power consumption models for each of the source, relay and destination nodes. We design low-complexity energy-efficient methods for jointly allocating resources at the SN and RN in the unconstrained, single power, dual power and sum-rate constrained optimization problems; the complexity of our methods for solving the unconstrained and sum-rate constrained optimization problems are similar to that of the water-filling method. It has been stated in [18], [20] that the SE-based joint SN and RN resource allocation problem is non-
convex. However, we show here that the EE-based objective function for the joint SN and RN resource allocation can be approximated by a convex function, and use this property for simplifying this objective function. We then derive explicit formulations of the near-optimal energy-per-bit as well as sub-channels’ power and rate for the unconstrained and constrained cases. In turn, we use these expressions for demonstrating that equal aggregate power allocation and allocating power to all the subchannels are the most energy-efficient power allocation in the unconstrained and general scenarios, respectively, at high channel gain-to-noise ratio.

The rest of the paper is organized as follows. Section II describes the two-hop MIMO-AF system in terms of achievable sum-rate, power consumption, and EE formulation based on the energy-per-bit consumption of the system, i.e. Joule-per-bit metric. In Section III, we first prove the existence of a unique global minimum for our EE-based objective function, simplify its formulation and detail how to solve the unconstrained and constrained EE optimization problems in a low-complexity manner, i.e. via one or two unidimensional searches. In Section IV, we first show the reliability and accuracy of our method in comparison with existing approaches as well as provide insights on the energy-efficient asymptotic allocation. As an application, we then compare the EE-optimal performances of two-hop MIMO-AF with MIMO systems. The results indicate that the usage of a relay must improve the quality of the two-hop link by about one order of magnitude in comparison with the direct link for the two-hop MIMO-AF to be more energy efficient than the MIMO system. Our results also show that the extra fixed power consumption induced by transmitting over two hops disadvantage MIMO-AF over MIMO system in terms of EE. However, using a relay can be useful for downsizing the donor cell, which in turn provides EE improvement and overall power consumption reduction at the expense of a lower sum-rate. Conclusions are drawn in Section V.

II. TWO-HOP MIMO AF SYSTEM AND POWER MODELS

A. System model

We consider a two-hop MIMO AF system composed of three nodes, i.e. an SN with $n$ antennas, a nonregenerative RN with $q$ antennas and a destination node (DN) with $r$ antennas, as it is depicted in Fig. 1. The SN transmits data to the RN via the RN over two phases of equal duration, as it has been fully detailed in [15] and [16], such that the aggregate mutual information (over two time slots) of this two-hop MIMO-AF system can be expressed as

$$I(y_2; s) = W \log_2 \left[ 1 + \frac{H_2 G H_1 R R^\dagger H_1^\dagger G H_2^\dagger}{\sigma_1^2 + \sigma_2^2 + \sigma_1^2 G H_2^\dagger H_2 G H_1 R R^\dagger} \right],$$  

(1)

where the matrices $H_1 \in \mathbb{C}^{q \times n}$ and $H_2 \in \mathbb{C}^{r \times q}$ represent the MIMO channels of the SN-RN and RN-DN links, respectively, the matrices $R \in \mathbb{C}^{n \times n}$ and $G \in \mathbb{C}^{q \times q}$ are precoding matrices at the SN and RN, respectively, and $\sigma_1^2$ and $\sigma_2^2$ are the variance of the Gaussian noise vectors $n_1 \in \mathbb{C}^{q \times 1}$ and $n_2 \in \mathbb{C}^{r \times 1}$, respectively. In addition, $W$ is the channel bandwidth, $I_x$ is a $x \times x$ identity matrix, $|.|$ is the matrix determinant, and $(.)^\dagger$ denotes the conjugate transpose.

An optimal precoder is the combination of an optimal precoder structure and an optimal power allocation. The Hadamard determinant theorem [34] establishes that an optimal precoder structure diagonalizes the matrix within the determinant in (1). In the case that the SN-RN link CSI is known at the SN as well as both the SN-RN and RN-DN links’ CSI is known at the RN, the SN and RN precoder structures of [15] or [16] have proved to be optimal for maximizing the SE, minimizing the transmit power, and optimizing the EE in [15], [35] and [33], respectively. Applying the SN and RN precoder structures of [15] into (1), the latter simplifies to

$$R_\Sigma(P) = W \sum_{m=1}^M \log_2 \left( 1 + \frac{p_{2,m} \lambda_{2,m} \sigma_2^2 + p_{1,m} \lambda_{1,m} \sigma_1^2}{1 + p_{2,m} \lambda_{2,m} \sigma_2^2 + p_{1,m} \lambda_{1,m} \sigma_1^2} \right),$$  

(2)

where $P = [p_{1,1}, \ldots, p_{1,M}, p_{2,1}, \ldots, p_{2,M}] \succeq 0$. In addition, $p_{1,m}$ and $p_{2,m}$ are the power elements of $P$ related to the SN and RN transmit powers, respectively, $\lambda_{i,m}$ denotes the non-zero eigenvalues of $H_i$, $i \in \{1,2\}$, $M = N \triangleq \min \{ \text{rk}(H_1), \text{rk}(H_2) \}$ is the total number of frequency-flat subchannels and $\text{rk}(\cdot)$ is the rank operator. Note that equation (2) is not only valid for the single-carrier two-hop MIMO-AF case but as well for the multi-carrier scenario [16], where $M = NK$ with $K$ being the number of frequency-flat subchannels. Furthermore, by defining $C_{1,m} = \log_2(1 + p_{1,m} \lambda_{1,m} \sigma_1^2)$ and $C_{2,m} = \log_2(1 + p_{2,m} \lambda_{2,m} \sigma_2^2)$ as the achievable rates over the $m$-th subchannel of SN-RN and RN-DN links, respectively, equation (2) can be re-expressed as

$$R_\Sigma(C) = W \sum_{m=1}^M C_{1,m} + C_{2,m} - \log_2 \left( 2^{C_{1,m} + 2^{C_{2,m} - 1}} \right),$$  

(3)

with $C = [C_{1,1}, \ldots, C_{1,M}, C_{2,1}, \ldots, C_{2,M}] \succeq 0$.

B. Power consumption model

Even though a base station (BS), a relay, and a user equipment (UE) are different in their architectures and components, it has been shown in {[8], [36], {[37], [38]} and [24], respectively, that their power consumption can be formulated in a similar manner via a linear relation between the consumed and transmit powers, such as

$$P_m = \Delta P + tPC, \quad \text{for the RF dependent and circuit (fixed) power consumptions, respectively. In addition, } t$$
number of transmit antennas and the transmit power, i.e. RF output power, is such that $P \in [0, P_{\text{max}}]$ with $P_{\text{max}}$ being the maximum transmit power. For instance, the total transmit powers at the SN and RN in a two-hop MIMO-AF system are usually bounded as [15]

$$
0 \leq P_i(P) = E\{\|\mathbf{R}_i\|_F^2\} \leq P_{i,\text{max}},
$$

respectively, where $E\{\cdot\}$ and $\|\cdot\|_F$ stand for the expectation and Frobenius norm. By inserting the optimal SN and RN precoder structures into (5) as well as knowing that $p_{1,m} = \Delta_1^{-1} A_{1,m}(2^{C_{1,m}} - 1)$ and $p_{2,m} = \Delta_2^{-1} A_{2,m}(2^{C_{2,m}} - 1)$, $P_i(P)$ in (5) can be re-expressed as

$$
P_i(C) \triangleq \Delta_i^{-1} \sum_{m=1}^{M} A_{i,m}(2^{C_{i,m}} - 1),
$$

for any $i \in \{1, 2\}$, with $A_{i,m} \triangleq \Delta_i^{-2} \Delta_i^{-1} a_{i,m}$.

Given the two-phase transmission, the SN will either transmit or be inactive, the RN will either receive or transmit, and the DN will either receive or be inactive. Accordingly, these different types of power consumptions should be reflected in the power model, as in [8] for the BS. Let $P_{\text{Tx}}$, $P_{\text{Rx}}$, $P_{\text{Sl}}$ be the transmit, receive and sleep mode powers for any of the nodes, the total power consumed over two time slots by the two-hop MIMO-AF system of Fig. 1 can then be expressed as

$$
P_{\Sigma} = (P_{\text{Tx}}^{\text{SN}} + P_{\text{Rx}}^{\text{RN}} + P_{\text{Sl}}^{\text{DN}}) + (P_{\text{Sl}}^{\text{SN}} + P_{\text{Rx}}^{\text{RN}} + P_{\text{Sl}}^{\text{DN}}).
$$

In the downlink scenario, the BS and UE are respectively the SN and DN such that $P_{\text{Tx}}^{\text{SN}} = \Delta_{\text{BS}} P_1(C)$, $P_{\text{Rx}}^{\text{RN}} = \Delta_{\text{RN}} P_2(C)$, $P_{\text{Rx}}^{\text{Gs}} = q P_{\text{Rx}}^{\text{UE}}$, $P_{\text{Sl}}^{\text{SN}} = \gamma q P_{\text{Sl}}^{\text{UE}}$ as well as $P_{\text{Sl}}^{\text{DN}} = \text{cr} P_{\text{Sl}}^{\text{UE}}$ in (7). Hence, based on equation (4)’ linear model, $P_{\Sigma}$ can be re-expressed as

$$
P_{\Sigma}(C) = P_c + \sum_{i=1}^{2} \Delta_i P_i(C),
$$

where $\Delta_1 = \Delta_{\text{BS}}$, $\Delta_2 = \Delta_{\text{RN}}$, $P_c = n P_{\text{GS}} + (1+\gamma) q P_{\text{Rx}}^{\text{UE}} + r P_{\text{Sl}}^{\text{UE}}$, and $\gamma$ denotes the ratio between transmission and reception overhead powers with $0 \leq \gamma \leq 1$. Intuitively, receiving consumes less overhead power than transmitting. Similarly, $P_{\Sigma}(C)$ can be obtained as in (8) for the uplink but where the BS and UE are the DN and SN, respectively.

### C. EE formulation

The existence of a trade-off between EE and SE implies that EE and SE cannot be optimized separately. Thus, in order to optimize this trade-off, one has first to explicitly formulate it as an objective function. In theory, the EE-SE trade-off of a point-to-point communication system consuming a total power of $P_{\Sigma}$ Watt for achieving a total rate of $R_{\Sigma}$ bit/s over a bandwidth $W$ (Hz) can be formulated as [39]

$$
\frac{E_b}{N_0} = \frac{C^{-1}(C)}{C},
$$

where

$$
E_b \triangleq P_{\Sigma}/E_{\text{bb}}
$$

is the transmitted energy per information bit and $N_0$ (Joule) is the noise power spectral density. In addition, $C$ is the channel capacity per unit bandwidth of the system and $C^{-1}(C)$ is its inverse function such that $C^{-1}(C) = P/\sigma^2$, with $\sigma^2 = N_0 W$. According to (9), the energy-per-bit consumption, $E_b$, or EE, $1/E_b$, of the two-hop MIMO-AF system can simply be expressed as the ratio of its total consumed power to its sum-rate, which are given in (8) and (3), respectively, such that

$$
E_b(C) = \frac{P_c + \sum_{i=1}^{2} \sum_{m=1}^{M} A_{i,m} (2^{C_{i,m}} - 1)}{W \sum_{m=1}^{M} C_{1,m} + C_{2,m} - \log_2(2^{C_{1,m}} + 2^{C_{2,m}} - 1)}.
$$

### III. TWO-HOP MIMO-AF EE OPTIMIZATION

In this section, we first show that $E_b$ in (10) has a unique global minimum and, then, utilize this property for simplifying this $2M$-variable objective function into a $M$, $M$, $M + 1$ and $M + 2$-variable functions in the unconstrained, sum-rate, single power and dual power constrained EE optimization problems, respectively. We then show that these joint SN and RN resource optimization problems can be formulated in a similar manner as in the single-hop MIMO scenario. Next, we adapt our method of [27] to the MIMO-AF scenario for further simplifying these problems and solving them in a low-complexity manner; a complexity similar to the classic water-filling algorithm in both the unconstrained and sum-rate constrained cases. In the process, we also obtain explicit formulations of the near-optimal energy-per-bit consumption, subchannels’ power and rate for the unconstrained and constrained scenarios.

**Proposition 1:** The function $E_b$ in (10) has a unique global minimum occurring at $C^*$, such that $E_b(C) > E_b^* = E_b(C = C^*)$ for $C \geq 0$, $C \neq C^*$. See Section A of the Appendix for the detailed proof of this proposition.

**Proposition 2:** Given that $E_b$ in (10) has a unique global minimum, its formulation simplifies to $E_b(C) = \text{...}$

In addition, $\mu^*$ is the optimal value of $\mu$, which is a slack variable used in the power constrained optimization cases; in the unconstrained and sum-rate constrained cases, $\mu^1 = \mu^2 = 1$. Thus, the $2M$-variable function in (10) simplifies into a $M$, $M + 1$ or $M + 2$-variable function in (11) when $C = C^*$. Note that $C_{1,m}$ and $C_{2,m}$ can be expressed as a function of $C_m$ in (12) such that

$$
C_{m} \triangleq C_{1,m} + C_{2,m} - \log_2(2^{C_{1,m}} + 2^{C_{2,m}} - 1).
$$

where $\mathcal{T} \triangleq \text{mod} \{i, 2\} + 1$ with $\text{mod} \{\ldots\}$ being the modulo operator. See Section B of the Appendix for the detailed proof of this proposition.
Remark 1: Given that $2^x - 1 \leq \sqrt{2^x (2^x - 1)} \leq 2^x$ for any $x \geq 0$, $E_b(C)$ in (11) can be lower and upper bounded as

$$P_c + \sum_{m=1}^{M} \frac{A_m^{-1} (2^{c_m} - 1)}{W \sum_{m=1}^{M} C_m} \leq E_b(C) \leq 2 \frac{P_c - P_c + \sum_{m=1}^{M} A_m^{-1} (2^{c_m} - 1)}{W \sum_{m=1}^{M} C_m},$$

where $A_m \triangleq (A_{1,m} + A_{2,m} + \sqrt{\frac{\mu^*_1}{\mu_2} + \sqrt{\frac{\mu^*_2}{\mu_1}}} \sqrt{A_{1,m} A_{2,m}})^{-1}$,

$$P_c \triangleq P_c + \frac{1}{2} \left( \sqrt{\frac{\mu^*_1}{\mu_2}} + \sqrt{\frac{\mu^*_2}{\mu_1}} \right) \sum_{m \in M^*} \sqrt{A_{1,m} A_{2,m}}.$$ (14)

and $M^* = \{ m \in M | C_m^* > 0 \}$ is the optimal set of allocated subchannel indices with $M = \{1, \ldots, M \}$.

Remark 2: Note that the two convex functions lower and upper bounding $E_b(C)$ in (11) are formulated in the same manner than $E_b(C)$ for the MIMO system with CSI [27], i.e.

$$E_b(C) = \frac{P_c + \sum_{m=1}^{M} B_m^{-1} (2^{c_m} - 1)}{W \sum_{m=1}^{M} C_m},$$ (15)

where $B_m = (\Delta B^M \sigma^2)^{-1} \lambda_m$, $P_0 = n P_{BS}^{\text{CSI}} + \zeta_r P_{DE}^{\text{CSI}}$ and $\lambda_m$ is the channel gain for each subchannel. In the two-hop MIMO-MAF scenario, $A_m$ acts as an aggregate channel gain, which encompasses both the channel gains of the SN-RN and RN-DN channels for each subchannel, and $P_c \geq 0$.

Proposition 3: According to (11), the optimal value of $E_b(C)$, i.e. $E_b^* \triangleq E_b(C = C^*)$, can be expressed as

$$E_b^* = \frac{\ln(2)}{W} \frac{2^{c_m^*}}{2} \left[ \sum_{i=1}^{2} \mu^*_i A_{i,m} + \sqrt{\frac{\mu^*_1}{\mu_2} + \frac{\mu^*_2}{\mu_1}} \sum_{i \in M^*} \sqrt{A_{1,i,m} A_{2,i,m}} \left( 2^{c_m^*} - 1 \right) \right],$$ (16)

in the unconstrained as well as constrained scenarios, where $C_m^*$ is the optimal value of $C_m$ for any $m \in M^*$. The full proof of this proposition is provided in Section C of the Appendix.

Corollary 1: A direct consequence of Proposition 3 is that any $c_m^*$ can be formulated in closed-form as a function of $E_b^*$ and $\mu^*_i$, $i \in \{1, 2\}$, by solving the following cubic equation

$$a_{3,m} (2^{c_m^*})^3 + a_{2,m} (2^{c_m^*})^2 + a_{1,m} (2^{c_m^*}) + a_{0,m} = 0,$$

where

$$a_{3,m} = (\mu^*_1 A_{1,m} - \mu^*_2 A_{2,m})^2,$$

$$a_{2,m} = -2 (W E_b^* (\mu^*_1 A_{1,m} + \mu^*_2 A_{2,m}) / \ln(2) + a_{3,m}),$$

$$a_{1,m} = (W E_b^* / \ln(2))^2 - \mu^*_1 \mu^*_2 A_{1,m} A_{2,m} - a_{2,m} - a_{3,m},$$

$$a_{0,m} = - (W E_b^* / \ln(2))^2.$$ (17)

Consequently, the optimal value of $C_m$ is such that

$$c_m^* = \left[ \log_2 \left( \frac{a_{2,m}}{3a_{3,m}} + 1 + \frac{1}{6a_{3,m}} \sqrt{\frac{1}{2} \left( \Theta_m + \sqrt{\Theta_m^2 - \Lambda_m} \right)} \right) \right] + \frac{1 - \sqrt{3}}{6a_{3,m}} \left[ \sqrt{\frac{1}{2} \left( \Theta_m - \sqrt{\Theta_m^2 - \Lambda_m} \right)} \right],$$ (18)

for any $m \in M^*$, where $[x] = \max\{x, 0\}$, $\Theta_m = 2a_{3,m}^2 - 9a_{3,m} a_{2,m} A_{1,m} + 27a_{3,m} a_{0,m}$, and $\Lambda_m = (a_{2,m}^2 - 3a_{3,m} a_{1,m})^3$.

Corollary 2: Given that $\sqrt{2^x (2^x - 1)} \approx 2^x - 0.5$, i.e. they differ by less than 1% for $x \geq 2$, $E_b(C)$ in (11), $P_i(C)$ in (6) and $E_b^*$ in (16) can be well-approximated by

$$E_b(C) \approx \frac{\bar{P}_c + \sum_{m \in M^*} A_m^{-1} (2^{c_m} - 1)}{W \sum_{m \in M^*} C_m},$$ (19a)

$$P_i(C) \approx \bar{P}_i(C) = \sum_{m \in M^*} \left( A_{1,m} + \sqrt{\frac{\mu^*_1}{\mu_2} \sqrt{A_{1,m} A_{2,m}}} \right) \left( 2^{c_m} - 1 \right) - \frac{A_m}{2}$$ and

$$E_b^* \approx E_b^*(\tilde{C}^*) = \ln(2) W^{-1} \tilde{A}_m^{-1} \tilde{2}^{\tilde{c}_m},$$ (19c)

respectively, where

$$\tilde{A}_m \triangleq \left( \sqrt{\mu^*_1 A_{1,m}} + \sqrt{\mu^*_2 A_{2,m}} \right)^{-2}$$ (20)

in (19c). Assuming that subchannel $l$ and $m$ are active, equation (19c) yields the following relation between $\tilde{C}_l$ and any $\tilde{c}_m$ such that, for any $(l, m) \in M^*$,

$$\tilde{C}_l = \tilde{C}_m + \log_2 \left( \tilde{A}_m / \tilde{A}_l \right).$$ (21)

A. Unconstrained EE Optimization

In the unconstrained scenario, the EE-based joint optimization problem is such that

$$\min_C E_b(C) \text{ s.t. } C \geq 0,$$ (22)

with $\mu^*_1 = \mu^*_2 = 1$ in $E_b(C)$ in (11) and $\tilde{A}_m = A_m = (\sqrt{A_{1,m} A_{2,m}})^{-2}$ in (20). Knowing that (11) is approximately equal to (19a), $E_b(C^*)$ becomes a single variable function which can be approximated as

$$E_b^* \approx \frac{M^* A_{1,m}^{-1} \tilde{2}^{\tilde{c}_m} - \sum_{l \in M^*} A_{l}^{-1} + \bar{P}_c}{W \left[ M^* (C_m^* - \log_2(A_m)) + \sum_{l \in M^*} \log_2(A_l) \right]},$$ (23)

by inserting (21) into (19a), where $M^*$ is the optimal number of allocated subchannels ($1 \leq M^* \leq M$) and $\bar{P}_c = P_c + \sum_{l \in M^*} \sqrt{A_{l,1,l} A_{1,l}}$ according to (14). Next, by inserting (21) into (19c) and then substituting the left side of (23) with the right side of (19c), we can derive an approximation of $C_m^*$ in closed-form as

$$\tilde{c}_m^* = \frac{1}{\ln(2)} \left[ W_0 \left( \frac{\bar{P}_c - \sum_{l \in M^*} A_{l}^{-1}}{M^* \sum_{l \in M^*} \frac{1}{\frac{1}{\Pi_{l \in M^*} A_{l}}} - \tilde{2}} \right) + 1 \right] - \sum_{l \in M^*} \log_2(A_l) - \log_2(A_m),$$ (24)

for any $m \in M^*$, and $\tilde{c}_m^* = 0$ otherwise. In addition, $W_0$ denotes the real branch of the Lambert function [40]. Similarly to the MIMO case in [27], the value of $E_b^*$ can then be obtained by applying a simple binary-search type of algorithm on $M^*$, i.e. by finding the number of allocated subchannels that minimizes $E_b^*$. Note that this process is EE-optimal in the MIMO case but only suboptimal in the MIMO-MAF case since (19c) and (23) are only approximations of $E_b^*$. In order to refine the process and obtain near-optimal $C_m^*$ and $E_b^*$ values, we can use Corollary 1. Indeed, we can refine $\tilde{c}_m^*$ by inserting $\tilde{E}_b^*$ into (17) and (18) and, then, refine $\tilde{E}_b^*$ by inserting the updated $\tilde{c}_m^*$ into (11), as it is summarized in Algorithm 1.
**Algorithm 1** Unconstrained optimization

1: function UN-Controlled optimization
2: Compute $C^*_m$ in (24) for any $m \in \{1, U\}$
3: Obtain $E_0^b = E_0(C)$ by inserting $C^*_m$ into (11)
4: Refine $C^*_m$ by inserting $E^*_b$ into (17) and (18)
5: Refine $E^*_b$ by inserting $C^*_m$ into (11)
6: return $C^*_m$ and $E^*_b$
7: end function

8: Inputs: $M, W, P_c$, and $A_{i,m}$ for $i \in \{1, 2\}$ and $m \in \mathcal{M}$
9: Set $U = M$ and $\mu_1 = \mu_2 = 1$
10: while $\frac{1}{\mu} > \frac{\frac{1}{\mu} \Delta_i}{\frac{1}{\mu} \Delta_i}$ do $U = U - 1$
11: Obtain $M^* \in \{1, U\}, C^*_m$ and $E^*_b$ via a binary-search on UN-CC
12: Outputs: $C^*_m$ and $E^*_b$

**B. Sum-rate Constrained EE Optimization**

Assuming an end-to-end sum-rate constraint, i.e., over two-hops, the EE-based joint optimization problem is such that

$$\min_{\mathcal{C}} E_0(\mathcal{C})$$

subject to

$$\mathcal{C} \geq 0, R_{\Sigma}(\mathcal{C}) \geq R_{\min}.$$  (25)

In the case that $R_{\Sigma}(\mathcal{C}) > R_{\min}$ for $\mathcal{C} = \mathcal{C}^*$, the EE-optimal unconstrained solution of (22), which can be obtained via Algorithm 1, is also the solution of (25). Otherwise, when the rate constraint is enforced, i.e., $R_{\Sigma}(\mathcal{C}) = R_{\min}$ in (25), then $E_0(C) = \frac{P_{\max}}{\mu}$ and, hence, the EE-based optimization problem in (25) reverts to a power minimization problem with the following associated Lagrangian

$$\mathcal{L}(\mathcal{C}, \nu) = P_{\Sigma}(\mathcal{C}) + \nu (R_{\min} - R_{\Sigma}(\mathcal{C})),$$  (26)

where $\nu$ is a slack variable. As it is explained in Section C of the Appendix, solving $\nabla \mathcal{L}(\mathcal{C}^*, \nu^*) = 0$ yields relation (16) but with $\nu^*$ instead of $E^*_b$ in the left side of (16). Therefore, we can use Corollary 1 to formulate $C^*_m$ as a function of $\nu^*$ (by replacing $E^*_b$ with $\nu^*$ and setting $\mu_1 = \mu_2 = 1$ in (17) and (18)), where $\nu^*$ acts as a water-level. Then, we can obtain the optimal $\nu^*$ as well as $C^*_m$ in a low-complexity manner by using a simple water-filling approach such that $R_{\Sigma}(\mathcal{C}(\nu^*)) - R_{\min} = 0$. Alternatively, knowing that (24) simplifies to

$$\tilde{C}^*_m = \begin{cases} \frac{1}{M^*} \left( \frac{R_{\min}}{\mu} - \sum_{t \in \mathcal{M}^*} \log_2(A_t) \right) + \log_2(A_m), & \forall m \in \mathcal{M}^* \\ 0, & \text{otherwise} \end{cases} (27)$$

when $R_{\Sigma}(\mathcal{C}) = R_{\min}$, we can use a similar algorithm as in the unconstrained scenario, which is summarized in Algorithm 2.

**Algorithm 2** Sum-rate constrained optimization

1: function SRC($U, W, P_c, R_{\min}, \mu_i, A_{i,m}$)
2: Compute $C^*_m$ in (27) for any $m \in \{1, U\}$
3: Same as lines 3 and 4 of UNCC
4: Set $C^*_m = C^*_m R_{\min}/\left(\sum_{t=1}^{U} C_t\right)$ (Normalization);
5: Refine $E^*_b$ by inserting $C^*_m$ into (11)
6: return $C^*_m$ and $E^*_b$
7: end function

8: Inputs: $M, W, P_c, R_{\min}$, and $A_{i,m}$ for $i \in \{1, 2\}$ and $m \in \mathcal{M}$
9: Set $U = M$ and $\mu_1 = \mu_2 = 1$
10: while $\frac{1}{\mu} > \frac{\frac{1}{\mu} \Delta_i}{\frac{1}{\mu} \Delta_i}$ do $U = U - 1$
11: Obtain $M^* \in \{1, U\}, C^*_m$ and $E^*_b$ via a binary-search on SRC
12: Outputs: $C^*_m$ and $E^*_b$

of (28). Whenever this condition is not met, we design a low-complexity near-optimal algorithm for both the single and dual power constrained cases in Algorithm 3.

1) Single Transmit Power Constrained at the SN or RN:

In the case that the SN or RN transmits at full power, then $P_i(C) = P_i^\max$ ($i = 1$ or 2) in (28) and the Lagrangian associated to the optimization problem in (28) is given by

$$\mathcal{L}(\mathcal{C}, \tilde{\mu}_i) = [P_c + \Delta_i (1 - \tilde{\mu}_i R_{\Sigma}(\mathcal{C}))] P_i^{\max} + \Delta_i P_i(\mathcal{C}) + \tilde{\mu}_i R_{\Sigma}(\mathcal{C}) \Delta_i P_i(\mathcal{C}) R_2(\mathcal{C})^{-1}.$$  (29)

where $\tilde{\mu}_i$ is a slack variable. Given that $P_i(C) = P_i^\max$, we can approximate $C^*_m$ by inserting (21) into $P_i(\mathcal{C})$ in (19b) as

$$\tilde{C}^*_m = \log_2 \left( \frac{\Delta_i P_i^{\max} + \sum_{t \in \mathcal{M}^*} \Delta_i \Sigma_t \beta_t(m)}{\sum_{t \in \mathcal{M}^*} \Sigma_t \beta_t(m)} \left( \frac{\mu^*}{\mu^* A_{i,m}} + \frac{\mu^* A_{i,m}}{\mu^* A_{i,m} + \sqrt{A_{i,m}} A_{i,m}} \right) \right).$$  (30)

where $\mu^* = \mu_1 / \mu_2$, $\mu_1 = \tilde{\mu}_1 R_{\Sigma}(\mathcal{C}^*), \forall i \in \{1, 2\}$, and

$$\beta_t(m) = \frac{\mu^* A_{i,m}}{\mu^* A_{i,m} + \sqrt{A_{i,m}} A_{i,m}}.$$  (31)

Note that $\mu^* = 1$ in the single power constrained case.

In addition, according to equations (13)(50) and (48), $C^*_i$, which relates to $\tilde{C}^*_m$ and $\tilde{C}^*_i$, respectively, as follows

$$\tilde{C}^*_i = \log_2 \left( 1 + \frac{\mu^* A_{i,m}}{\mu^* A_{i,m} + \sqrt{A_{i,m}} A_{i,m}} \right)$$  (32a)

$$\tilde{C}^*_i = \log_2 \left( 1 + \frac{\mu^* A_{i,m}}{\mu^* A_{i,m} + \sqrt{A_{i,m}} A_{i,m}} \right)$$  (32b)

where $\tilde{C}^*_i$ and $P_i$ as a function of $\tilde{C}^*_i$ are provided in (13) and (50), respectively. By using (30) in conjunction with (32) and the latter result into (12), we can obtain a robust approximation of $\tilde{C}^*_i$ solely as a function of $\mu^*$, as it is indicated in our single power constrained (SPC) function. Then, by inserting the latter into (11), we can expressed $E^*_b$ solely as a function of $M^*$ and $\mu^*$. For a given $M^*$, $\mu^*$ can be obtained by using a unidimensional search algorithm on $\mu^*$, e.g. Golden section search, Newton-Raphson method, etc. [41]. Knowing that (11)
and (16) are equal for $\mu_i^* \in C^*$, $\mu_i^*$ can also be obtained in closed-form as a function of $C^*$, such that

$$
\mu_i^* = \left( -\frac{b_2}{3b_3} + \sum_{k=1}^2 \left[ \frac{1 + j2^{k-1}}{b_3} \frac{\sqrt{2}}{\sqrt{1 + 2^{k-1}}} \right] \right)^2$

(33)

where $\Theta = 2b_2^2 - 9b_3b_2b_1 + 27b_2^2b_0$, $\Lambda = (4b_2^2 - 3b_3b_1)^3 - b_0 - \sum_{m=1}^{U-1} A_{1,m}A_{2,m}(2c_{1m}^n - 1)$, $b_1 = \frac{ln(2)}{U} \sum_{m=1}^U C_{1m}$, $b_2 = \frac{ln(2)}{U} \sum_{m=1}^U C_{1m}^2 - \left( \sum_{m=1}^U c_{1m}^n \right) - A_{1m,A_{2,m}}^n (2c_{1m}^n - 1)$, $b_3 = \frac{ln(2)}{U} \sum_{m=1}^U C_{1m}^3 - \left( \sum_{m=1}^U c_{1m}^n \right) \sum_{m=1}^U c_{1m}^n A_{1m}$.

2) Dual Transmit Power Constrained at the SN and RN:

In the case that both the SN and RN transmit at full power, the Lagrangian associated to the EE optimization problem in (28) can be expressed as $L(C, \tilde{\mu}_1, \tilde{\mu}_2) = R_L(C)^{-1} \times \left( P_c + \sum_{i=1}^2 \Delta_i \left[ (1 - \tilde{\mu}_i)R_2(C) \right] P_{1m}^{max} + \tilde{\mu}_i R_2(C) P_1(C) \right)$. (34)

This problem is equivalent to optimizing the sum-rate subject to both the SN and RN transmitting at full power. Although, this problem has been investigated in the literature [18], [20] from an SE perspective, we solve it here from an EE perspective. Similar to the single power constraint case, $C_{1m}$ can be formulated solely as a function $\mu_i^*$ as in (30). Given that $C_{1m}^*$ must be identical for $i = 1$ and $i = 2$, $\mu_i^*$ can be obtained from (30) by solving a quadratic equation, such that

$$
\mu_i^* = \frac{1}{4} \left( \frac{c_1c_2 - c_0c_3}{c_0c_4 - c_2c_5} + \sqrt{\frac{(c_1c_2 - c_0c_3)^2}{c_0c_4 - c_2c_5} + \frac{4c_1c_4 - c_3c_5}{c_0c_4 - c_2c_5}} \right)^2$

(35)

with $c_0 = \Delta_1 P_{1m}^{max} + \sum_{i=1}^U A_{1,i}$, $c_1 = \Delta_2 P_{2m}^{max} + \sum_{i=1}^U A_{2,i}$, $c_2 = \sum_{i=1}^U \tilde{\beta}(\mu_i^*) A_{1,i}$, $c_3 = \sum_{i=1}^U \tilde{\beta}(\mu_i^*) A_{2,i}$, $c_4 = \sum_{i=1}^U \tilde{\beta}(\mu_i^*) A_{1,i} A_{2,i}$ and $c_5 = \sum_{i=1}^U A_{1,i} A_{2,i}/2$. Next, $C_{1m}^*$ is obtained by inserting $\mu_i^*$ into (30) and, then, refined by using (32a) and (12). Knowing that (11) and (16) are equal for $\mu_i^*$ and $C = C^*$, $\mu_i^*$ can be expressed in closed-form as a function of $C_{1m}^*$ and $\mu_i^*$, such that $\mu_i^* = \frac{U}{2m} E_b(C)^{*} \times \left( \sum_{m=1}^U 2c_{1m}^* \left( \mu_i A_{1,m} + A_{2,m} \right) \right)$

(36)

where $E_b(C)^*$ is given in (11) for $M = U$. More details about the dual power constrained (DPC) function are given above.

D. Energy-efficient MIMO-AF procedure

The unconstrained EE optimization problem becomes either a rate maximization or power minimization problem when either both the SN and RN transmit at full power or the two-hop link cannot support a target rate, respectively. Thus, EE optimization is a generalization of both SE and power optimizations such that enforcing rate or power constraints on EE provides either a power or SE-optimal solution, which, however, is suboptimal in terms of EE. The sole EE-optimal
solution is the unconstrained EE solution. Consequently, Algorithm 1 must first be used to find the optimal unconstrained energy-efficient joint SN and RN resource allocation. If $W \sum_{m \in M} C^*_m \leq R_{\text{min}}$, then the allocation is refined by using Algorithm 2. Similarly, if $P_1(C^*) \geq P_1^{\text{max}}$ or $P_2(C^*) \geq P_2^{\text{max}}$, then the allocation is refined by using Algorithm 3. At the end of the algorithm near-optimal values of $C^*_{1,m}$ and $C^*_{2,m}$ are obtained by inserting $\mu_1^*$, $\mu_2^*$ and $\tilde{C}^*_{m}$ into (13). Whereas, near-optimal values of $p^*_{1,m}$ and $p^*_{2,m}$ are obtained by inserting $C^*_{1,m}$ and $C^*_{2,m}$ into $p_{1,m} = \Delta_1^{-1} A_{1,m} (2\tilde{C}^*_{m} - 1)$ and $p_{2,m} = \Delta_2^{-1} A_{2,m} (2\tilde{C}^*_{m} - 1)$, respectively. Note that as in [15], [33], we assume that the eigenvalues $\lambda_{1,m}$ and $\lambda_{2,m}$ are sorted in descending order for each link prior to using our algorithms.

### E. Algorithms’ accuracy results

In order to demonstrate the reliability of our algorithms, i.e. Algorithms 1, 2 and 3, for jointly optimizing the SN and RN resource allocation in an energy-efficient manner, we compare their results, averaged over 1000 runs, against the holistic results of [33] and those of the Matlab “fmincon” function in Figs. 2 and 3. Given that $E_0$ is quasiconvex, one can solve the optimization problems in (22), (25) and (28) via usual convex optimization tools such as the Matlab “fmincon” function.

We depict in Figs. 2 and 3, the unconstrained and single transmit power, dual transmit power as well as sum-rate constrained results, respectively, as a function of the RN and DN noise powers for various numbers of subchannels, power and rate constraint values. These figures are plotted by assuming a MIMO Rayleigh fading channel between each node and using the values of Table 1, when considering a macro BS (MaBS) at the SN, for setting the various power parameters of Section II-B. Moreover, $W = 1$ as well as $\varsigma = 0.5$, and $\sigma^2 = 0$ dB in Fig. 3. The results clearly show the tight match between our algorithm results and the “fmincon” function results for both the unconstrained as well as constrained scenarios, and regardless of the numbers of subchannels and constraint values. In turn, it graphically confirms the great accuracy and reliability of our low-complexity energy-efficient joint SN and RN resource allocation method for the two-hop MIMO-AF system. Moreover, our algorithms outperform the holistic approach in [33] for $R_{\text{min}} = 20$ bit/s and provide similar results to [33] in the other settings.

### IV. INSIGHTS, APPLICATIONS AND RESULTS

#### A. EE MIMO-AF Optimization insights

Let us define $p_m \triangleq A_m^{-1} (2\tilde{C}^*_{m} - 1)$ as the per-subchannel aggregate transmit power such that $2\tilde{C}^*_{m} = A_m p_m + 1$. The optimal per-subchannel aggregate transmit power can then be approximated as

$$p^*_m \approx \tilde{p}^*_m = \left(\frac{\hat{A}_m W E^*_b / \ln(2) - 1}{2}\right)^+$$

by substituting $2\tilde{C}^*_{m}$ with $A_m \tilde{p}^*_m + 1$ in (19c). Given that $\hat{A}_m$ increases as both $A_{1,m}$ and $A_{2,m}$ decrease,
\[ p_m = W E_b / \ln(2) \]

\[ \tilde{p}_{i,m}^* = \frac{\sigma_i^2 [\tilde{A}_m W E_b / \ln(2) - 1]}{\lambda_{i,m}} \left( 1 + \sqrt{\frac{\mu_2 A_{i,m}}{\rho_i^2 A_{i,m}}} \right). \]  (38)

In order to verify our previous premises, we depict in Fig. 4 the total transmit powers at the SN as well as RN, and the EE-optimal SN and RN per-subchannel transmit and aggregate transmit powers as a function of the noise power \( \sigma_i^2 \) for \( \sigma_1^2 = \sigma_2^2 \). We consider \( M = 4 \) subchannels for each link with the following gain values \( \lambda_1 = [5.1, 3.7, 2.1, 0.9] \) and \( \lambda_2 = [3.9, 2.7, 2.2, 1.1] \). We also set \( W = 1 \), \( P_1^{\text{max}} = 20 \) W, \( P_2^{\text{max}} = 10 \) W, and the other power parameter values according to Table I. It can be seen in the first subplot that at high noise power, the optimal total transmit powers at both SN and RN are constrained. As the noise power decreases (as \( A_{i,m} \) increases), as the optimal total transmit powers become progressively unconstrained, from \( \sigma_1^2 = -9 \) and \( \sigma_2^2 = -32 \) dB onwards for the SN and RN transmit powers, respectively. Equivalently, it can be remarked in the three lower subplots that at high noise power, allocating all the power to the best subchannel is energy efficient; in better channel condition (when \( \sigma_1^2 \) decreases), optimal EE is obtained by sharing the power between subchannels, i.e., breakpoint at \( \sigma_1^2 = 12 \), \( \sigma_2^2 = 8 \) and \( \sigma_2^2 = 2 \) dB for the second, third and fourth subchannels on the three lower subplots. These results confirm our premise that allocating power to all the \( M \) subchannels is EE-optimal when the aggregate channel gain-to-noise ratio is high. Moreover, the results regarding \( p_m \) (in the second subplot) confirms that equal aggregate power allocation is the most energy efficient power allocation in the unconstrained scenario since all the \( p_m^* \) converge towards \( W E_b / \ln(2) \). Finally, the graphs show the great accuracy of our asymptotic expressions for the EE-optimal SN and RN per-subchannel transmit powers in (38).

B. Application: EE comparison of MIMO-AF with MIMO systems

As an application for our algorithms, we compare the EE of MIMO and MIMO-AF systems with CSI, and analyze in which scenarios MIMO-AF can be more energy efficient than MIMO systems.

1) MIMO-AF vs. MIMO EE insights: Firstly, MIMO-AF incurs extra power consumption in comparison with a MIMO system due to the usage of a relay and the two-phase communication. Hence, \( P_0 \) in the energy-per-bit formulation of the MIMO system in (15) is always lower than \( P_c \) in (19a). Secondly, it can easily be proved from (12) that the per-subchannel aggregate rate \( C_m \) can be bounded as follows

\[ \min \{C_{1,m}, C_{2,m}\} \leq C_m \leq \min \{C_{1,m}, C_{2,m}\}. \]

In other words, \( C_m \) can only be as good as the worst of the two links' rate. Consequently, these two disadvantages make MIMO-AF always less energy-efficient than MIMO if the channel gain-to-noise ratio of both systems are equivalent, i.e. \( B_{0,m} \) in (15) is equal to \( A_{1,m} \) in (19a).

In Fig. 5, we depict the minimum channel gain improvement, averaged over 10000 runs, that the usage of a relay must achieve for MIMO-AF to be more energy efficient than MIMO as a function of the MIMO noise power, \( \sigma^2 \), in MIMO Rayleigh fading when \( M = 8 \), \( \sigma_1^2 = \sigma_2^2 \). Given that regardless of the configuration this minimum channel gain improvement is positive (> 5 dB), it confirms that the usage of a relay must
provide channel gain improvement for MIMO-AF to be more energy-efficient than MIMO systems. In the unconstrained scenario MIMO-AF must improve the quality of each link by at least 10 dB, i.e. about one order of magnitude. Whereas less channel improvement is required from MIMO-AF when the SN transmit power is constrained; in this case, MIMO achieves a suboptimal EE, as it is explained in Section III-D, whereas, MIMO-AF can fine-tune the power at the RN for improving the EE. However, the graph also indicates that MIMO-AF capability to improve the EE is largely diminished when the RN transmit power is constrained; indeed, the second hop acts as a bottleneck in this case.

2) MIMO-AF vs. MIMO EE results: In a realistic system, the channel gain improvement translates into pathloss improvement. Assuming a simple distant-dependent pathloss model such that \( P_{\text{th}} = 10^{\alpha_d \log_{10}(d)} \) and knowing that a relay can at best split the SN-DN distance by half for each hop, we can expect a channel gain improvement of \( 3\alpha \) dB by using a relay, where \( \alpha \) is the pathloss exponent, \( \Gamma \) is a constant and \( d \) is the distance. Hence, relaying is likely to be more beneficial in terms of EE when the direct channel quality is poor, i.e. for high values of \( \alpha \). This also echoes the results of Fig. 5, where the minimum channel gain improvement decreases as the direct link quality worsens, i.e. when \( \sigma^2 \) increases.

In order to illustrate this hypothesis, we compare in Figs. 6 and 7, the EE-optimal transmit power, consumed power, sum-rate and energy-per-bit of MIMO-AF and MIMO systems, averaged over 10000 runs, by taking into account both pathloss and small scale (Rayleigh) fading. We also consider practical simulation parameter values, which are reported in Table II, MaBS or Micro BS (MiBS) at the SN, \( M = 256 \), i.e. \( N = 2 \) & \( K = 128 \), and the linear layout of Fig. 1 such that \( D, \alpha D \) and \( (1 - \alpha)D \) are the SN-DN, SN-RN and RN-DN distances, respectively. In both figures, we utilize the following pathloss model between two nodes

\[
\rho = 10^{\frac{(G_{\text{RX}} - \text{PL}(d))}{10}},
\]

where \( G_{\text{TX}} \) is the antenna gain, and \( \text{PL}(d) = P_{\text{LOS}}(d) \times \text{PL}_{\text{LOS}}(d) + (1 - P_{\text{LOS}}) \text{PL}_{\text{NLOS}}(d) \) is the distance dependent path-loss function. In addition, \( P_{\text{LOS}} \) is the line-of-sight (LOS) probability, \( \text{PL}_{\text{LOS}}(d) \) and \( \text{PL}_{\text{NLOS}}(d) \) are the LOS and non-LOS (NLOS) path-loss functions, whose values can be found in Table 33 of [42]. Note that we considered here \( P_{\text{LOS}} \) for the suburban scenario, i.e. scenario 2 in Table 33 of [42].

The total transmit power results in the upper-left corner of Figs. 6 and 7 indicate that the usage of a relay can be beneficial for reducing the transmit power since for most RN positions, especially when \( D = 2 \) km in Fig. 7, the total transmit power consumption of MIMO is greater than the one of MIMO-AF, i.e. \( P_1 + P_2 \). However, this reduction in transmit power does not translate into reduction in total consumed power. Indeed, \( P_2 \) of MIMO-AF is far higher than \( P_2 \) of MIMO in the upper-right corner of both figures, because MIMO-AF induces extra overhead power such as the BS sleeping mode power. In terms of sum-rate, the results in the lower-left corner of Figs. 6 and 7 show that MIMO-AF can improve the latter by more than 50% when the RN is close to the DN. Indeed, given that the transmit power of the RN is 20 times lower than that of the MaBS, the EE-optimal transmit power of the RN is constrained when it is far from the DN and, hence, the second hop acts as

<table>
<thead>
<tr>
<th>Parameters (Unit)</th>
<th>Values</th>
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</thead>
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<tr>
<td>( f_c ) (GHz)</td>
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</tr>
<tr>
<td>( W ) (MHz)</td>
<td>10</td>
</tr>
<tr>
<td>( N_0 )</td>
<td></td>
</tr>
<tr>
<td>( \text{(dBm/Hz)} )</td>
<td></td>
</tr>
<tr>
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<tr>
<td>UE to UE</td>
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<tr>
<td>( G_{\text{TRX}} ) (dBi)</td>
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</tr>
<tr>
<td>BS to UE</td>
<td></td>
</tr>
<tr>
<td>BS to RN</td>
<td>14</td>
</tr>
<tr>
<td>RN to UE</td>
<td>5</td>
</tr>
</tbody>
</table>

![Fig. 6: Comparison of the EE-optimal transmit power, consumed power, sum-rate and energy-per-bit of MIMO-AF against MIMO for practical settings and \( D = 0.5 \) km.](image)

![Fig. 7: Comparison of the EE-optimal transmit power, consumed power, sum-rate and energy-per-bit of MIMO-AF against MIMO for practical settings and \( D = 2 \) km.](image)
bottleneck, as we previously remarked in Fig. 5. The sum-rate improvement translates into an EE improvement in the lower-right corner of Fig. 7 but only when $D = 2$ km. It confirms that relaying is mainly beneficial in terms of EE when the direct channel quality is poor, i.e. when the DN is far from the SN (cell edge user). However, this EE improvement is solely the result of sum-rate improvement and not power reduction. If now we consider that the BS sleeping mode power, $P_{BS}^{SLEEP}$, is equal to zero, i.e. the BS is switched off during the second transmission phase, or that a MiBS ($G_{TXR_{BS}}$ to RN = 7 dBi, see Table I for power parameter values) is used instead of the MaBS at the SN for the MIMO-AF system, then the usage of MIMO-AF can really be beneficial in terms of EE. This in line with the fact that the amount of transmit power that is required for being energy efficient decreases as the circuit power decreases in the MIMO system [43]. It can be remarked in the lower-part of Figs. 6 and 7, that some of the extra sum-rate provided by MIMO-AF can really be beneficial in terms of EE. This see Table I for power parameter values) is used instead of the MaBS at the SN, which in turn, reduces the energy-per-bit consumption. Finally, it is worth noting that the positioning of the relay is an important factor for the MIMO-AF system to be or not to be energy efficient.

V. CONCLUSION

In this paper, a low-complexity energy-efficient joint resource allocation method has been designed for the two-hop MIMO-AF system when considering that full CSI is available at the RN and transmit CSI is available at the SN. We have demonstrated how to simplify the multivariate unconstrained, power and sum-rate constrained EE problems into single or dual variate problems by proving that our EE-based objective function has a unique global minimum and showing its similarity with the single-hop MIMO scenario. Based on this insight, we have derived explicit formulations of the near-optimal energy-per-bit consumption, subchannels’ rate and power for all our EE optimization problems of interest and provided algorithms for solving these problems in a low-complexity manner. These explicit formulations have also been utilized for showing that equal aggregate power allocation and full subchannel allocation are the most energy-efficient strategies in the unconstrained and general cases, respectively, when the channel gain-to-noise ratio is high. Simulations have demonstrated in various scenarios that our method is both reliable and accurate when compared to a classic optimization method and the iterative method of [33]. As an application, we have compared the EE-optimal performances of the two-hop MIMO-AF and MIMO systems with CSI. The results have indicated that the usage of a relay must improve the link quality by around one order of magnitude per hop for the two-hop MIMO-AF to be more energy-efficient than the MIMO system, when the relay is mid-way between the SN and DN. Our results have also indicated that the extra fixed power consumption induced by transmitting over two hops does not disadvantage MIMO-AF over MIMO systems in terms of EE. Reducing this fixed power consumption and placing the relay wisely are two important factors for MIMO-AF to be more energy efficient than MIMO systems. In the future, we would like to generalize this work for any number of hops and to include the duplexing ratio in the optimization process.

APPENDIX

A. Proof for Proposition 1

Proof: The function $E_b$ in (10) is continuous and twice differentiable such that its gradient and Hessian can be expressed as

$$\nabla E_b(C) = \frac{\nabla P_{\Sigma}(C) R_{\Sigma}(C) - \nabla R_{\Sigma}(C) P_{\Sigma}(C)}{R_{\Sigma}(C)^2}$$

and (39a)

$$\nabla^2 E_b(C) = \frac{\nabla^2 P_{\Sigma}(C) R_{\Sigma}(C) - \nabla R_{\Sigma}(C) P_{\Sigma}(C)}{R_{\Sigma}(C)^2}$$

+ $\frac{\nabla R_{\Sigma}(C)^T \nabla E_b(C) + \nabla E_b(C)^T R_{\Sigma}(C)}{R_{\Sigma}(C)}$, (39b)

respectively, where $\{ \cdot \}^T$ is the transpose operator. In addition,

$$\nabla P_{\Sigma}(C) = \ln(2) [A_{11} z_{1,1}^{C_{1,1}}, \ldots, A_{21} z_{2,1}^{C_{2,1}}, \ldots, A_{2M} z_{2,M}^{C_{2,M}}],$$

(40a)

$$\nabla^2 P_{\Sigma}(C) = \ln(2) \text{ diag} \{ \nabla^2 P_{\Sigma}(C) \},$$

(40b)

where $\text{diag} \{ \cdot \}$ is the diagonal operator, and

$$\nabla^2 R_{\Sigma}(C) = W \left[ \begin{array}{c} 2^{C_{2,1}} - 1 \\ 2^{C_{2,1}} + 2^{C_{2,2}} - 1 \\ \vdots \\ 2^{C_{2,1}} + 2^{C_{2,2}} - 1 \\ 2^{C_{1,1}} - 1 \\ 2^{C_{1,1}} + 2^{C_{2,1}} - 1 \\ \vdots \\ 2^{C_{1,1}} + 2^{C_{2,1}} - 1 \\ 2^{C_{1,1}} + 2^{C_{2,2}} - 1 \\
\end{array} \right].$$

(41a)

$$\{ \nabla^2 R_{\Sigma}(C) \}_{(i,m),(j,l)} = \frac{\partial^2 R_{\Sigma}(C)}{\partial C_{i,m} \partial C_{j,l}} = \begin{cases} -W \ln(2) \frac{2^{C_{i,m}} - 1}{2^{C_{i,m}} + 2^{C_{1,m}} - 1} & \text{if } i = j \text{ and } l = m \\
W \ln(2) \frac{2^{C_{i,m}} + 2^{C_{1,m}} - 1}{2^{C_{i,m}} + 2^{C_{1,m}} - 1} & \text{if } i = 7 \text{ and } l = m \\
0 & \text{otherwise.} \\
\end{cases}$$

(41b)

According to (39b), $\nabla E_b(C) z^T = 0$ implies that $R_{\Sigma}(C) z \nabla^2 E_b(C) z^T = z \nabla^2 R_{\Sigma}(C) z^T P_{\Sigma}(C)$, or equivalently with (40b) that $R_{\Sigma}(C) z \nabla^2 E_b(C) z^T = \ln(2) z \cdot (\nabla P_{\Sigma}(C) R_{\Sigma}(C) z^T) - z \nabla^2 R_{\Sigma}(C) z^T P_{\Sigma}(C)$, where $\cdot$ denotes the dot product. In addition, since $\nabla P_{\Sigma}(C) R_{\Sigma}(C) z^T = \nabla R_{\Sigma}(C) P_{\Sigma}(C) z^T$ when $\nabla E_b(C) z^T = 0$, $z \nabla^2 E_b(C) z^T$ can be re-expressed as

$$z \nabla^2 E_b(C) z^T = \frac{\ln(2) P_{\Sigma}(C)}{R_{\Sigma}(C)^2} \left( z \cdot (\nabla R_{\Sigma}(C) z^T) - z \nabla^2 R_{\Sigma}(C) z^T \right)$$

$$= \frac{W \ln(2) P_{\Sigma}(C)}{R_{\Sigma}(C)^2} \sum_{m=1}^{M} H_m(C),$$

(42)

where

$$H_m(C) = 2^{C_{1,m} + C_{2,m}} (z_{1,m} - z_{2,m})^2 + 2^{C_{1,m}} (2^{C_{1,m}} - 1)^2.$$

Since $H_m(C) \geq 0$ when $C_{i,m} \geq 0$, for any $i \in \{1, 2\}$ and $m \in M = \{1, \ldots, M\}$, we can conclude that $\nabla E_b(C) z^T = 0 \Rightarrow z \nabla^2 E_b(C) z^T \geq 0$ for any $C \geq 0$ such that $E_b$ is quasiconvex.
over its domain, i.e., unimodal, according to (3.21) of [41]. In other words, $E_b$ can have several local minima, but it has a global minimum value. Note that any local minima, which are not global, are not strict minima [44].

Let $C^*$ be a stationary point of $E_b$, accordingly, $\nabla E_b(C) = 0$. Moreover, we know from (39a) that if $\nabla E_b(C)|z^T = 0$ then $E_b(C) = \frac{\nabla P_\Sigma(C)(z^T - 1)^T}{\ln(2)} R_\Sigma(C + z)$ such that $E_b(C + z) - E_b(C) = \frac{\nabla P_\Sigma(C)(z^T - 1)^T \cdot [R_\Sigma(C + z) - R_\Sigma(C)] \nabla P_\Sigma(C) z^T}{R_\Sigma(C + z) \nabla R_\Sigma(C) z^T}$. (43)

In addition, let $F : \mathbb{R} \mapsto \mathbb{R}$ and $\|z\| \ll 1$, then the gradient of $F$ is similar to

$$\nabla F(z)^T = F(z + 1) - F(z).$$

Given that $\nabla P_\Sigma(C)(z^T - 1)^T > \ln(2) \nabla P_\Sigma(C) z^T$, for $z \neq 0$, it implies with (43) and (44) that $E_b(C + z) > E_b(C*)$. Consequently, any stationary point is a strict local minima and, hence, according to theorem 6.2 of [44], a strict global minima of $E_b$.

B. Proof for Proposition 2

Proof: On the one hand, by inserting (12) into equations (3) and (6), the latter can be re-expressed as

$$R_\Sigma(C) = W \sum_{m=1}^{M} C_m,$$

$$P_i(C) = \Delta_i \sum_{m=1}^{M} A_i[m] \left(2^{C_m} - 1\right) = 1 + 2^{C_i,m} \left(2^{C_m} - 1\right),$$

respectively. On the other hand, according to (39a) and (29) as well as (34), solving $\nabla E_b(C) = 0$ and $\nabla L(C^*, \nu^*) = 0$ as well as $\nabla L(C^*, \nu^*) = 0$ in the unconstrained and power constrained scenarios yield $E_b^* = E_b(C^*) = \frac{\partial P_\Sigma(C)}{\partial C_i,m} \left[\frac{\partial R_\Sigma(C)}{\partial C_i,m}\right]^{-1}$, (45a)

$$\mu_i \frac{\partial P_\Sigma(C)}{\partial C_i,m} \left[\frac{\partial R_\Sigma(C)}{\partial C_i,m}\right]^{-1} = \mu_i \frac{\partial P_\Sigma(C)}{\partial C_i,m} \left[\frac{\partial R_\Sigma(C)}{\partial C_i,m}\right]^{-1},$$

respectively, for any $i \in \{1, 2\}$ and $m \in M^e$, where $\mu_i = \frac{2^{C_i,m} \left(2^{C_m} - 1\right)}{\mu_i \left(2^{C_m} - 1\right)}$.

C. Proof for Proposition 3

Proof: Similar to (46), solving $\nabla E_b(C) = 0$, $\nabla L(C^*, \nu^*) = 0$, $\nabla L(C^*, \mu_i, \mu_2) = 0$ and $\nabla L(C^*, \mu_i, \mu_2) = 0$ in the unconstrained, sum-rate constrained as well as single and dual power constrained scenarios with respect to $C_m$ yield

$$E_b^* = \left(\mu_i^* \frac{\partial P_\Sigma(C)}{\partial C_m} + \mu_2^* \frac{\partial P_\Sigma(C)}{\partial C_m} \left[\frac{\partial R_\Sigma(C)}{\partial C_m}\right]^{-1}\right)^{-1},$$

where $\mu_i^* = \mu_2^* = 1$ in the unconstrained as well as sum-rate constrained cases, and $\mu_i^* = 1$ or $\mu_2^* = 1$ in the single power constrained case. Note that $E_b^*$ is replaced by $\nu^*$ in the sum-rate constrained case. In addition, $\frac{\partial P_\Sigma(C)}{\partial C_m} = W$ and $\frac{\partial P_\Sigma(C)}{\partial C_m} = \frac{\ln(2) \cdot 2^{C_m} - 1}{4 \mu_i^*}$, (45b)

$$\Delta_i \sum_{m=1}^{M} A_i[m] \left(2^{C_i,m} - 1\right) \sqrt{2^{C_m} - 1},$$

according to (45a) and (50), respectively. By inserting these results into (51), equation (16) can then be obtained.

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